# Regression and Classification

#### Samuel Cheng

School of ECE University of Oklahoma

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S. Cheng (OU-ECE)

Regression and Classification

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$$\nabla f(\mathbf{x})|_{(0,1,0)} = (0,0,2)^T$$

# Loss function for regression

Let us start with the regression problem. Recall from previously that

• We are trying to learn a function f(x; W) such that for training input  $x_i$  and desired output  $y_i$ ,  $f(x_i; W) \sim y_i$ 

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• For regression, it is common to use mean square error for loss function, i.e.,  $l(f(x_i; W), y_i) = (f(x_i; W) - y_i)^2$ 

For example, try to predict the mass (weight) of a man based on his height, bmi, and his age (assuming we don't know what bmi is here)

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• Write  $X_{train} = (x_1, x_2, \cdots, x_N)$  and  $y_{train} = (y_1, y_2, \cdots, y_N)^T$ , we want

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# RegressionLinear regressionanalytical solution

Assume that the mean square loss is used. We want to minimize

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Linear regression

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- MSE: 6.63. It is a bit high, let's try to reduce it

# Expanding features...

• Let's include some higher "order" features. For the raw feature  $x_1, x_2, x_3$ , we can also include products of them as a feature. So a new feature vector becomes

$$(1, x_1, x_2, x_3, x_1^2, x_2^2, x_3^2, x_1x_2, x_1x_3, x_2x_3),$$

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- We can do linear regression just as before, just the number of weights increases from 4 to 10
- MSE: 1.01. Nice!

• Let's go even higher order and also include products like  $x_1x_2x_3$ and  $x_1^2x_2$ . So the new feature vector now becomes

$$(1, x_1, x_2, x_3, x_1^2, x_2^2, x_3^2, x_1x_2, x_1x_3, x_2x_3, x_1^3, x_2^3, x_3^3, x_1^2x_2, \cdots)$$

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- MSE: 0.32...

# Expanding features (con't)...

- We can go further to the 4-th order and the number of weights now increases to 70
- MSE: 1.13e-12. Wow!

## Wait, how about testing error?



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Regression and Classification

## Wait, how about testing error...? Oops



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# Curve fitting

Why is it so bad for testing? Let's visit another even simpler example

• Let's try to fit a quadratic curve  $y = (x - 3)^2$  with linear regression. And again our training data will be wiggled a little bit by a Gaussian noise



# Curve fitting (2nd order)

Let's include higher order feature just as before. Take  $(1,x,x^2)$  as feature by including  $x^2$ 



Example: curve fitting

## Curve fitting (3rd order)

 $\left(1,x,x^2,x^3\right)$ 



Example: curve fitting

# Curve fitting (4th order)

 $\left(1,x,x^2,x^3,x^4\right)$ 



Example: curve fitting

# Curve fitting (5th order)

 $\left(1,x,x^2,x^3,x^4,x^5\right)$ 



# Curve fitting (6rd order)

 $\left(1, x, x^2, x^3, x^4, x^5, x^6\right)$ 



# Curve fitting (7rd order)

 $\left(1, x, x^2, x^3, x^4, x^5, x^6, x^7\right)$ 



# Curve fitting (8th order)

 $(1, x, x^2, x^3, x^4, x^5, x^6, x^7, x^8)$ 



# Curve fitting (9th order)

 $(1, x, x^2, x^3, x^4, x^5, x^6, x^7, x^8, x^9)$ 



# Overfitting vs underfitting



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• Given sufficiently complex model, we can learn "anything", but ...

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  - Unlike optimization, we don't actually know the true objective function
  - Loss function is just an approximated goal

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  - It is testing error but not training error that actually counts
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  - Unlike optimization, we don't actually know the true objective function
  - Loss function is just an approximated goal
- Should try to avoid neither overfitting nor underfitting

- Given sufficiently complex model, we can learn "anything", but ...
  - Machine learning is all about generalization
  - It is testing error but not training error that actually counts
- Machine learning is very similar to optimization, we just try to find our best model by minimizing a loss function, but...
  - Unlike optimization, we don't actually know the true objective function
  - Loss function is just an approximated goal
- Should try to avoid neither overfitting nor underfitting
  - Everything should be made as simple as possible, but not simpler Albert Einstein
  - Occam's razor: overly complex model is not a good thing (if you don't have sufficient data to fit the model)

## High-bias vs high-variance

Sometimes we also refer to overfitting and underfitting roughly as high-variance and high-bias



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# High-bias vs high-variance

Sometimes we also refer to overfitting and underfitting roughly as high-variance and high-bias

- High-bias: model is too rigid to learn (thus biased) and it cannot adapt to the data
- High-variance: model is too elastic and can fit any arbitrary data. When fitted with different training data, the weights just converge to totally different values (thus high variance)



# More on overfitting (high-variance)

- In the high-variance domain, the model is essentially learning the training data noise. That's why weights converge to different values for different training data
- Model complexity is relative. If more training data are available, the model used to be overfitted may not be overfitted anymore. So should we change a model every time we added new data?!



## New perspective?!



Figure 1: Curves for training risk (dashed line) and test risk (solid line). (a) The classical *U-shaped risk curve* arising from the bias-variance trade-off. (b) The *double descent risk curve*, which incorporates the U-shaped risk curve (i.e., the "classical" regime) together with the observed behavior from using high capacity function classes (i.e., the "modern" interpolating regime), separated by the interpolation threshold. The predictors to the right of the interpolation threshold have zero training risk.

Rather than using a simple model, we could restrain a more complex model from running wild with additional constraints. This process is commonly known as regularization

- As regularization can mitigate the overfitting problem, we can use a more expressive model even when we have only few data. And the same model can be used as data size increases
- A regularized complex model typically outperforms an unregularized simple model

## Ridge regression

A most common type of regularization is by restraining the magnitudes of the weights
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• For example, in ridge regression, we try to achieve this by simply including  $\frac{1}{2}\lambda \mathbf{w}^{T}\mathbf{w}$  in the loss objective function. Thus

$$L(\mathbf{w}) = \frac{1}{2} (\mathbf{y} - \mathbf{X}^{\mathsf{T}} \mathbf{w})^{\mathsf{T}} (\mathbf{y} - \mathbf{X}^{\mathsf{T}} \mathbf{w}) + \frac{1}{2} \lambda \mathbf{w}^{\mathsf{T}} \mathbf{w}$$

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$$= \frac{1}{2} \left( \mathbf{y}^{\mathsf{T}} \mathbf{y} - \mathbf{w}^{\mathsf{T}} \mathbf{X} \mathbf{y} - \mathbf{y}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}} \mathbf{w} + \mathbf{w} [\mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda \mathbf{I}] \mathbf{w} \right)$$

• And the gradient is

$$\nabla_{\mathbf{w}} L(\mathbf{w}) = -X\mathbf{y} + [XX^{T} + \lambda I] \mathbf{w}$$

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• As before, if we set  $\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}) = 0$ , we have

$$\mathbf{w} = [XX^T + \lambda I]^{-1}X\mathbf{y}$$

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### Lasso

• Another common regularization is lasso. Instead of  $\lambda \mathbf{w}^T \mathbf{w}$ , the scaled  $l_1$ -norm of  $\mathbf{w}$ ,  $\lambda \|\mathbf{w}\|_1$  is added to the loss objective function Thus, we want to

$$\min_{\mathbf{w}} \frac{1}{2} (\mathbf{y} - \boldsymbol{X}^{\mathsf{T}} \mathbf{w})^{\mathsf{T}} (\mathbf{y} - \boldsymbol{X}^{\mathsf{T}} \mathbf{w}) + \lambda \|\mathbf{w}\|_{1},$$

where  $\|\mathbf{w}\|_1 = |w_1| + |w_2| + \dots + |w_D|$ 

<sup>&</sup>lt;sup>1</sup>The ridge regression function in the 0.18.1 version of sciki-learn appears to have bug. Both ridge regression and lasso function are implemented as lasso  $\Xi \to \Xi$ 

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  - We will discuss how the optimization is typically performed later
  - $\bullet\,$  For the next several slides, I just used sciki-learn library ^1 in Python

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  - We will discuss how the optimization is typically performed later
  - $\bullet\,$  For the next several slides, I just used sciki-learn library ^1 in Python
- Lasso tends to enforce a sparse weight solution. It was popular several years ago because of compressed sensing

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- Machine learning is all about generalization (from data)
- One can decrease the training error to arbitrarily small (by increasing model complexity)
- On the other hand, we really only care about test error, which is composed of
  - Bias: High bias when model is too rigid (model complexity is too low) to adapt to the training data
  - Variance: High variance when model is too flexible (model complexity is too high) that different sets of training data will converge to completely different weight parameters
- Occam's razor: a good explanation should be minimal

- For supervised learning systems (both classification and regression), we can typically reduce it to an optimization problem of minimizing a loss function (instead of training error) w.r.t. some weights
- Regularization terms can typically be incorporated in the loss function to keep the weights from running wild
- It is almost always better to use a more complex but regularized model than a simple model when one has sufficient training data
  - Provided that one regularized wisely
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  - That is why deep neural networks typically work better
    - Actually with sufficient data, we don't need to worry about overfitting
    - Furthermore, sometimes you may even want to overfit a small training set (attain 0 training error but large testing error) just to make sure your model is correct

### Linear classification

The same linear regression idea can be transferred to classification problems

- Consider binary classification whether an image contains a cat or not
  - We can first vectorize the input image into a column vector **x** (with an extra 1 appended to account for bias)

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• We will decide if the image contains a cat of not by verifying if

$$\mathbf{x}^T \mathbf{w} \leq \mathbf{0},$$

where we will need to obtain the weight w through training (more later)

### Logistic regression

• We can introduce a scoring function

$$f(\mathbf{x}; \mathbf{w}) = H(\mathbf{x}^{\mathsf{T}} \mathbf{w}),$$

where  $H(t) = \begin{cases} 1, & t \ge 0\\ 0, & t < 0 \end{cases}$  is a step function and we have a cat if f(x; w) = 1 and no cat if f(x; w) = 0

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- Note that f(x; w) essentially is a perceptron model and is difficult to train because of the discontinuity of  $H(\cdot)$ . Instead, we could replace  $H(\cdot)$  by the sigmoid (or logistic) function  $S(t) = \frac{1}{1+e^{-t}}$ 
  - Hence, known as logistic regression

### Loss function of logistic regression

Another advantage of using  $S(\cdot)$  is that we can interpret the output as probability and then the loss function can be specified by a "cross-entropy loss" as follows (will explain next)

$$L(\mathbf{w}; \mathbf{x}) = \begin{cases} -\log f(\mathbf{x}; \mathbf{w}), & \text{if the image is a cat} \\ -\log(1 - f(\mathbf{x}; \mathbf{w})), & \text{otherwise} \end{cases}$$

#### Multi-class classification

## Softmax classifier



• For multiclass problem, we can extend the logistic scoring function to

$$f_i(\mathbf{x}; W) = \sigma_i(W\mathbf{x}),$$

where  $\sigma_i(\mathbf{y}) = \frac{\exp(y_i)}{\sum_j \exp(y_j)}$  is known as a softmax function and is really just a normalized exponential function

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• Again, we can interpret  $f_i(\mathbf{x};W)$  as the estimated probability of  $\mathbf{x}$  belong to class i

• E.g., 
$$p(cat; x, W) = f_{cat}(x; W)$$



• Let say the image is actually a dog. We can express this as a distribution as shown on the left



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- Ideally we would like the estimated probability distribution matches the actual one
- We can measure the difference between two distributions with KL-divergence given by

$$\mathcal{KL}(q\|p) = \sum_{i} q_i \log \frac{q_i}{p_i}$$

$$egin{aligned} &\mathcal{KL}(p\|q) = \sum_i p_i \log_2 rac{p_i}{q_i} \ &= -\sum_i p_i \log_2 rac{q_i}{p_i} \end{aligned}$$

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### Fact

For any real x,  $\ln(x) \le x - 1$ . Moreover, the equality only holds when x = 1

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Regression and Classification

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### Classification Multi-class classification Cross entropy loss function (con't)

- KL-divergence is a way to estimate the difference between two distribution
  - $KL(q||p) \ge 0$  and KL(q||p) = 0 if and only if  $q \equiv p$

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Classification

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- We can pick KL(q||p) as the loss function, then

$$L(W; \mathbf{x}) = KL(q || p) = \sum_{i} q_{i} \log \frac{q_{i}}{p_{i}} = -\underbrace{\left[-\sum_{i} q_{i} \log q_{i}\right]}_{entropy} + \underbrace{\left[-\sum_{i} q_{i} \log p_{i}\right]}_{cross-entropy}$$

Multi-class classification

$$=-\sum_i q_i \log p_i$$
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$$=-\sum_{i}q_{i}\log p_{i}=-\log p_{j(\mathbf{x})}=-\log f_{j(\mathbf{x})}(\mathbf{x};W)=-\log \sigma_{j(\mathbf{x})}(W\mathbf{x}),$$

where j(x) is the actual class index of x

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where  $j(\mathbf{x})$  is the actual class index of  $\mathbf{x}$ 

• The total loss is just sum over all training x:  $L(W) = \sum_{x} L(W; x)$ 

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 with  $\Delta W = \epsilon \nabla_W L(W)$ ,

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 $\bullet$  So to optimize, we need to find the gradient of L wrt W

### Derivative of softmax loss

• Recall that  $L(W) = \sum_{x} L(W; x) = -\sum_{x} \sum_{j} q_{j}^{(x)} \log \sigma_{j}(Wx)$ , where  $q_{j}^{(x)}$  is non-zero (= 1) only when j is the true label of x

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  - Using chain rule,

$$\frac{\partial}{\partial w_{i,j}} L(W; \mathbf{x}) = \sum_{k} \frac{\partial}{\partial o_{k}} L(W; \mathbf{x}) \frac{\partial o_{k}}{\partial w_{i,j}} = x_{j} \frac{\partial}{\partial o_{i}} L(W; \mathbf{x})$$

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• We need to find  $\frac{\partial}{\partial o_i} L(W; \mathbf{x})$ 

# $\frac{\partial}{\partial o_i} L(W; \mathbf{x})$

• Recall  $L(W; \mathbf{x}) = \sum_{l} q_{l} \log \sigma_{l}(\mathbf{o})$  and  $\sigma_{l}(\mathbf{o}) = \frac{\exp(o_{l})}{\sum_{k} \exp(o_{k})}$ . It is easy to verify that  $\frac{\partial}{\partial o_{i}} \sigma_{j}(\mathbf{o}) = -\sigma_{i}(\mathbf{o})\sigma_{j}(\mathbf{o})$  and  $\frac{\partial}{\partial o_{i}} \sigma_{i}(\mathbf{o}) = \sigma_{i}(\mathbf{o})(1 - \sigma_{i}(\mathbf{o}))$ .

$$^{2}$$
o =  $W$ x

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<sup>2</sup>o = Wx
  
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### Stochastic gradient descent

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• One may go to the extreme and only pick one x to estimate the gradient. This formally is known as the stochastic gradient descent. But in practice, no one uses it. But people often say stochastic gradient descent when they actually mean mini-batch gradient descent

S. Cheng (OU-ECE)

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### Gradient descent with moment

• Going downhill reduces the error, but the direction of steepest descent does not point at the minimum unless the ellipse is a circle



<sup>2</sup>Slide borrowed from Hinton's courser course

Regression and Classification

### Gradient descent with moment

- Going downhill reduces the error, but the direction of steepest descent does not point at the minimum unless the ellipse is a circle
  - The gradient is big in the direction in which we only want to travel a small distance
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### Gradient descent with moment

- Going downhill reduces the error, but the direction of steepest descent does not point at the minimum unless the ellipse is a circle
  - The gradient is big in the direction in which we only want to travel a small distance
  - The gradient is small in the direction in which we want to travel a large distance
- A simple solution is to introduce "momentum" to the change of W. That is,

$$\Delta W = \lambda(\epsilon \nabla_W L(W)) + (1 - \lambda) \Delta W^{(old)}$$

• Will talk more about optimization methods later. So much for today

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# Remark on computing gradient

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### Remark on computing gradient

- For the previous discussion, we always assume that the gradient can be found analytically. In practice, it may not be true also
- But gradient of  $\mathcal{L}(W)$  can easily be computed numerically. For example, say  $W = \begin{pmatrix} 4.1 & 3.3 \\ -1.2 & 2.1 \end{pmatrix}$ ,

$$\frac{\partial}{\partial W_{1,1}} \mathcal{L}(W) \approx \frac{1}{h} \left[ \mathcal{L} \left( \begin{pmatrix} 4.1+h & 3.3\\ -1.2 & 2.1 \end{pmatrix} \right) - \mathcal{L} \left( \begin{pmatrix} 4.1 & 3.3\\ -1.2 & 2.1 \end{pmatrix} \right) \right]$$

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- Actually, the numerical gradient is useful even if an analytical gradient exists. It at least provides a mean to debug your system
  - And luckily, for some packages such as Theano, they automatically find the analytical gradient for you

## Conclusion

- For classification, we can feed the output of a linear regressor to a logistic function or softmax function to form a linear classifier
  - For only two classes, we have the logistic "regression" classifier
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- For classification, we can feed the output of a linear regressor to a logistic function or softmax function to form a linear classifier
  - For only two classes, we have the logistic "regression" classifier
  - For multi-class cases, we have the softmax classifiers
- For finding the optimal weights, we may not be able to get the solution right away analytically (possible though for linear regression and ridge regression)
  - Can optimize iteratively with gradient descent
  - Can speed up gradient descent by using mini-batch instead of full batch
  - Momentum is a common trick to improve optimization efficiency also



 Denote ŵ = w/||w||, ŵ ⋅ x<sub>1</sub> (ŵ ⋅ x<sub>-1</sub>) is the distance of the boundary line of x<sub>1</sub> (x<sub>-1</sub>) from the origin



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• SVM: for all  $x^{(i)}$ 

$$\max \frac{2}{\|\mathbf{w}\|}$$
 s.t.  $y_i(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1$ 



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• SVM: for all 
$$x^{(i)}$$

$$\max \frac{2}{\|\mathbf{w}\|} \quad s.t. \quad y_i(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1$$

Equivalently,

$$\min \|\mathbf{w}\|^2 \quad s.t. \quad y_i(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1$$

# KKT conditions

We can absorb the constraint using Lagrange multiplier and rewrite the optimization problem (why?) as

$$\min_{\mathbf{w},\boldsymbol{b}} \max_{\alpha_i \geq 0} \frac{1}{2} \|\mathbf{w}\|^2 - \sum_i \alpha_i (y^{(i)} (\mathbf{w} \cdot \mathbf{x}^{(i)} - \boldsymbol{b}) - 1)$$

Consider a slightly modified problem

$$\max_{\alpha_i \ge 0} \min_{\mathbf{w}, b} \frac{\frac{1}{2}}{\frac{1}{2}} \|\mathbf{w}\|^2 - \sum_i \alpha_i (y^{(i)} (\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1)$$

Generally speaking, the solution of the dual problem will be smaller. However, when the two solutions are the same the complementary slackness conditions  $\alpha_i^*(y^{(i)}(\mathbf{w}^* \cdot \mathbf{x}^{(i)} - b^*) - 1) = 0$  have to be satisfied. Together with  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1, \alpha_i \ge 0, \nabla_{\mathbf{w}} \mathcal{L} = 0$ , these are known as the KKT conditions, which are necessary condition for optimality

## Dual problem

Let's try to minimize L w.r.t. w and b

• 
$$\frac{\partial L}{\partial w} = 0 \Rightarrow w = \sum_{i} \alpha_{i} y^{(i)} x^{(i)}$$
  
•  $\frac{\partial L}{\partial b} = 0 \Rightarrow \sum_{i} \alpha_{i} y^{(i)} = 0$ 

Therefore the dual problem can now be rewritten as

$$\max_{\alpha_i \ge 0} \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y^{(i)} y^{(j)} \mathbf{x}^{(i)} \cdot \mathbf{x}^{(j)}$$

such that

$$\sum_{i} \alpha_i y^{(i)} = 0$$

# Support vectors

Say after solving the dual problem, we have

$$\mathbf{w} = \sum_{i} \alpha_i^* \mathbf{y}^{(i)} \mathbf{x}^{(i)}$$

Evaluating a new input x is simply computing the sign of

$$\mathbf{w} \cdot \mathbf{x} + \mathbf{b} = \sum_{i} \alpha_{i}^{*} \mathbf{y}^{(i)} \mathbf{x}^{(i)} \cdot \mathbf{x} + \mathbf{b}$$

Now, recall the complementary slackness condition  $\alpha_i^*(y^{(i)}(\mathbf{w}^* \cdot \mathbf{x}^{(i)} - b^*) - 1) = 0$ , actually most  $\alpha_i^*$  will be equal to 0 except those with corresponding  $\mathbf{x}^{(i)}$  "touching" the boundary, which are the support vectors

# Kernel trick

Note that during both evaluating and testing. We just need to manipulate the inner products among training features  $\mathbf{x}^{(i)}$  and with a new input  $\mathbf{x}$ 

- Potentially, we can increase the model complexity by evaluating these inner product projected to a higher dimensional space (including higher order monomials) without actually projection
- E.g.,  $\mathbf{x} = [x_1, x_2], \phi(\mathbf{x}) = [x_1 x_1, x_1 x_2, x_2 x_1, x_2 x_2]^\top$ ,  $\phi(\mathbf{x})^\top \phi(\mathbf{z}) = (\mathbf{x}^\top \mathbf{z})^2 \triangleq K(\mathbf{x}, \mathbf{z})$
- More generally, K(x, z) = (x<sup>T</sup>z + c)<sup>d</sup> corresponds to inner product of φ(x) including all monomials up to order d
- Generally, inner product can also be interpreted as the similarity between two vectors. One may think a reasonable (so-called Gaussian) kernel will be

$$\mathcal{K}(\mathbf{x},\mathbf{z}) = \exp\left(-rac{\|\mathbf{x}-\mathbf{z}\|^2}{2\sigma^2}
ight),$$

which actually corresponds to features projected to infinite  $\Xi$ 

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# Valid kernel (Mercer)

For any *m* vectors,  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(m)}$ , we can define a "kernel matrix"  $\mathcal{K}$  with  $\mathcal{K}_{i,j} = \mathcal{K}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$ . It is easy to verify that  $\mathcal{K}$  is symmetric (trivial) and positive semi-definite

- for any  $\mathbf{z} = [z_1, \cdots, z_m]^\top$ ,  $\mathbf{z}^\top \mathcal{K} \mathbf{z} = \sum_{i,j} z_i \phi(\mathbf{x}^{(i)})^\top \phi(\mathbf{x}^{(j)}) z_j = \sum_{i,j,k} z_i \phi_k(\mathbf{x}^{(i)}) \phi_k(\mathbf{x}^{(j)}) z_j = \sum_k \left( \sum_i z_i \phi_k(\mathbf{x}^{(i)}) \right)^2 \ge 0$
- Mercer Theorem: Mercer shows that if for any finite set of vectors, and the corresponding kernel matrix is symmetric positive semi-definite. The kernel will be a valid kernel (kernel output corresponding to the inner product of features mapped to some high dimensional space)

# Kernel PCA

- Principal component analysis (PCA) is a very common technique for dimension reduction. Consider data in high dimension, often data only vary along several dimensions and so we can keep dimensions for data with the highest variations and discard the rest
- The problem of PCA is that the analysis is linear. So for data like below, they are not separable
Consider the N *d*-dimensional data points as  $x^{(1)}, \dots, x^{(N)}$ . Assuming the project vectors in high dimensional are zero-mean (will come back to that later), the covariance matrix C at the high dimension can then be approximate by

$$C = \frac{1}{N} \sum_{i=1}^{N} \phi(x^{(i)}) \phi(x^{(i)})^{\top}$$

If we want to apply PCA at this high dimension, we need to eigen-decompose C. That is, we want to find v such that  $Cv = \lambda v$ . Amazingly, we have the following theorem regarding v

Support vector machine

#### Eigenvectors of projected space

#### Theorem (Eigenvectors)

Eigenvectors of C can be represented as weighted sum of  $\phi(x^{(i)})$ . That is,  $v = \sum_{i=1}^{N} \alpha_i \phi(x^{(i)})$ 

#### Proof.

Assume that  $Cv = \lambda v$ , thus

$$C\mathbf{v} = \frac{1}{N} \sum_{i=1}^{N} \phi\left(\mathbf{x}^{(i)}\right) \phi\left(\mathbf{x}^{(i)}\right)^{\top} \mathbf{v} = \lambda \mathbf{v}$$
$$\Rightarrow \mathbf{v} = \sum_{i=1}^{N} \underbrace{\frac{\phi\left(\mathbf{x}^{(i)}\right)^{\top} \mathbf{v}}{N\lambda}}_{\alpha_{i}} \phi\left(\mathbf{x}^{(i)}\right)$$

#### Gram matrix

The previous theorem gives us some ideas what eigenvectors in the high dimensional space are like. Let's substitute  $v = \sum_{i=1}^{N} \alpha_i \phi(x^{(i)})$  into  $Cv = \lambda v$ . We have,

$$\lambda \sum_{j=1}^{N} \alpha_{j} \phi\left(x^{(j)}\right) = \lambda \mathbf{v} = C \mathbf{v} = \frac{1}{N} \sum_{i=1}^{N} \phi\left(x^{(i)}\right) \phi\left(x^{(i)}\right)^{\top} \left(\sum_{j=1}^{N} \alpha_{j} \phi\left(x^{(j)}\right)\right)$$
$$= \frac{1}{N} \sum_{i=1}^{N} \phi\left(x^{(i)}\right) \left(\sum_{j=1}^{N} \alpha_{j} \phi\left(x^{(i)}\right)^{\top} \phi\left(x^{(j)}\right)\right)$$

Now let's define the Gram matrix G with its i, j element given by

$$G_{i,j} = \langle \phi\left(x^{(i)}\right), \phi\left(x^{(j)}\right) \rangle = \phi\left(x^{(i)}\right)^{\top} \phi\left(x^{(j)}\right) \triangleq \mathcal{K}(x^{(i)}, x^{(j)}),$$

where  $K(\cdot, \cdot)$  is the kernel function. For example, we can have the Gaussian kernel with  $K(x, y) = \exp(-||x - y||^2/c)$ 

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#### Solving for v

$$\lambda \sum_{j=1}^{N} \alpha_{j} \phi\left(x^{(k)}\right)^{\top} \phi\left(x^{(j)}\right) = \frac{1}{N} \sum_{i=1}^{N} \phi\left(x^{(k)}\right)^{\top} \phi\left(x^{(i)}\right) \sum_{j=1}^{N} \alpha_{j} \phi\left(x^{(i)}\right)^{\top} \phi\left(x^{(j)}\right)$$
$$\Rightarrow \lambda \sum_{j=1}^{N} \alpha_{j} G(k,j) = \frac{1}{N} \sum_{i=1}^{N} G(k,i) \sum_{j=1}^{N} \alpha_{j} G(i,j) \Rightarrow \lambda (G\alpha)_{k} = \frac{1}{N} \sum_{j=1}^{N} \alpha_{j} (G^{2})_{k,j}$$
$$\Rightarrow \lambda (G\alpha)_{k} = \frac{1}{N} (G^{2}\alpha)_{k} \Rightarrow \lambda G\alpha = \frac{1}{N} G^{2}\alpha \Rightarrow \lambda N\alpha = G\alpha$$

- Thus,  $\alpha$  is actually an eigenvector of G with eigenvalue  $\lambda N$
- Similar to the original PCA, we can sort the eigenvalues. And given  $\alpha$ , the eigenvector in  $\phi$ -space is  $v = \sum_{i=1}^{N} \alpha_i \phi(x^{(i)})$
- When receive a new input x, we can project to v as  $\langle \phi(x), v \rangle = \sum_{i=1}^{N} \alpha_i \langle \phi(x), \phi(x^{(i)}) \rangle = \sum_{i=1}^{N} \alpha_i K(x, x^{(i)})$

#### Support vector machine

# Centering $\phi(x^{(i)})$

We mentioned earlier that we have assumed  $\phi(x^{(i)})$  are zero-mean. In general, this is not true but can be easily fixed below. If  $\phi(x^{(i)})$  are not zero-mean,  $\phi(x^{(i)})$  should be replaced by  $\phi(x^{(i)}) - \frac{1}{N} \sum_{k=1}^{N} \phi(x^{(k)})$  instead. Thus we should have the correct Gram matrix

$$\begin{split} \tilde{G} \\ &= \left[ I_{N} - \frac{1}{N} \begin{pmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{pmatrix} \right]^{\top} \begin{pmatrix} \phi(x^{(1)})^{\top} \\ \vdots \\ \phi(x^{(N)})^{\top} \end{pmatrix} [\phi(x^{(1)}), \cdots, \phi(x^{(N)})] \left[ I_{N} - \frac{1}{N} \begin{pmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{pmatrix} \right] \\ &= \left[ I_{N} - \frac{1}{N} \begin{pmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{pmatrix} \right]^{\top} G \left[ I_{N} - \frac{1}{N} \begin{pmatrix} 1 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 1 \end{pmatrix} \right] \\ &= G - \frac{1}{N} I_{N} G - \frac{1}{N} G I_{N} + \frac{1}{N^{2}} I_{N} G I_{N}, \end{split}$$

where  $1_N$  is  $N \times N$  matrix with all ones

## Summary of Kernel PCA

- Decide a kernel and compute the normalized Gram matrix
- Eigen-decompose the normalized Gram matrix
- Sort the eigenvalues in the descending order. An eigenvector composes of the weights α for constructing the corresponding principal component in the φ-space
- Given an input x, the projection to a principal component with weight  $\alpha$  is given by  $\sum_{i=1}^{N} \alpha_i K(x, x^{(i)})$

#### Denoising with Kernel PCA

Now, consider K principal components  $v^{(1)}, \dots, v^{(K)}$  in  $(\phi$ -space) with

$$v^{(k)} = \sum_{i=1}^{N} \alpha_i^{(k)} \phi(x^{(i)}) \text{ for } k = 1, \cdots, K$$

We have a denoised version of x (let's call z here) if we only keep projection of x onto the K principal components in the  $\phi$ -space. That is,

$$\phi(z) = \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle v^{(k)}.$$

The problem is that it is not immediately clear how to find z to satisfy the above. So instead, let's try to minimize

$$L = \|\phi(z) - \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle v^{(k)} \|$$

#### Minimizing *L*

$$\begin{split} L &= \|\phi(z) - \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle v^{(k)} \| \\ &= \langle \phi(z), \phi(z) \rangle - 2 \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle \langle v^{(k)}, \phi(z) \rangle + \Omega \\ &= K(z, z) - 2 \sum_{i=1}^{N} \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle \alpha_i^{(k)} \langle \phi(x^{(i)}), \phi(z) \rangle + \Omega \\ &= K(z, z) - 2 \sum_{i=1}^{N} \sum_{k=1}^{K} \langle \phi(x), v^{(k)} \rangle \alpha_i^{(k)} K(x^{(i)}, z) + \Omega \\ &= K(z, z) - 2 \sum_{i=1}^{N} \gamma_i K(x^{(i)}, z) + \Omega \end{split}$$

Note that  $\Omega$  does not depend on z and hence can be ignored.

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#### Maximizing $\Lambda$

Now, if we focus on kernel with the form K(x, y) = K(||x - y||), the first term K(z, z) is a constant and can be ignored as well. So minimizing L is the same as maximizing

$$\Lambda = \sum_{i=1}^{N} \gamma_i K(x^{(i)}, z)$$

Let's maximize  $\Lambda$  by setting  $\nabla_z \Lambda$  to 0,

$$\nabla_{z}\Lambda = 2\sum_{i=1}^{N} \gamma_{i}K'(\|x^{(i)} - z\|^{2})(x^{(i)} - z) = 0$$
  
$$\Rightarrow z = \frac{\sum_{i=1}^{N} \gamma_{i}K'(\|x^{(i)} - z\|^{2})x^{(i)}}{\sum_{i=1}^{N} \gamma_{i}K'(\|x^{(i)} - z\|^{2})} = \frac{\sum_{i=1}^{N} \gamma_{i}e^{-\frac{\|x^{(i)} - z\|^{2}}{c}}x^{(i)}}{\sum_{i=1}^{N} \gamma_{i}e^{-\frac{\|x^{(i)} - z\|^{2}}{c}}}$$

Thus, we can iteratively update

$$z^{(m)} = \frac{\sum_{i=1}^{N} \gamma_i e^{-\frac{\|x^{(i)} - z^{(m-1)}\|^2}{c}} x^{(i)}}{\sum_{i=1}^{N} \gamma_i e^{-\frac{\|x^{(i)} - z^{(m-1)}\|^2}{c}}}$$

## Soft-margin SVM and hinge loss

• Hard-margin SVM

 $\min \|\mathbf{w}\|^2 \quad s.t. \quad y_i(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 \ge 0$ 



- Soft-margin SVM (allow constrain to be violate)
  - Define "hinge" loss function
    h(z) = max(0, z)
  - Want to minimize hinge loss

$$\sum_{i} h(1 - y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b))$$

• Soft-margin SVM

$$\min \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i h(1 - y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b))$$

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## Soft-margin SVM

One can reformulate the optimization problem as

• 
$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$
 such that  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1 - \xi_i, \xi_i \ge 0$ 

For the dual problem, write

$$L = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i - \sum_i \alpha_i [y^{(i)} (\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 + \xi_i] - \sum_i r_i \xi_i$$

We should minimize L w.r.t. w, b, and  $\xi_i$ . This gives us w =  $\sum_i \alpha_i y^{(i)} x^{(i)}, \sum_i \alpha_i y^{(i)} = 0$ , and  $C - \alpha_i - r_i = 0$ . So the dual problem can be rewritten as

$$\max_{\alpha} \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i} y^{(i)} y^{(j)} \alpha_{i} \alpha_{j} \mathbf{x}^{(i)} \mathbf{x}^{(j)}$$

such that  $0 \le \alpha_i \le C$ , and  $\sum_i \alpha_i y^{(i)} = 0$ 

#### Complimentary slackness conditions

Note that we have the conditions  $\alpha_i[y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 + \xi_i] = 0$  and  $r_i\xi_i = 0$ . Also  $C - \alpha_i - r_i = 0$  as we shown earlier, therefore

• If  $0 < r_i < C \Rightarrow 0 < \alpha_i < C$ ,  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 + \xi_i = 0$  and since  $\xi_i = 0$ ,  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) = 1$ 

• If 
$$r_i = 0$$
,  $\alpha_i = C$ ,  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 + \xi_i = 0$  but  $\xi_i \ge 0$ , therefore

$$y^{(i)}(\mathbf{w}\cdot\mathbf{x}^{(i)}-b)\leq 1$$

• If  $r_i = C$ ,  $\alpha_i = 0$ ,  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) - 1 + \xi_i \ge 0$  and since  $\xi_i = 0$ ,  $y^{(i)}(\mathbf{w} \cdot \mathbf{x}^{(i)} - b) \ge 1$ 

#### Sequential minimal optimization

- A major reason that SVM is so popular is that there are efficient methods in solving the optimization problem for training
- One popular method is SMO due to John Platt, the key idea is to select heuristically two  $\alpha$  at a time and fix the rest
  - Pick one of the  $\alpha$  that violates the KKT conditions. Pick the second  $\alpha$  that maximizes the optimization step
  - The remaining problem will be a simple quadratic optimization problem with closed form solution

#### Multi-class SVM

• We can easily extend soft-margin SVM to multi-class case. Let  $s_{l}(\mathbf{x}) = \mathbf{w}_{l}^{T} \begin{bmatrix} 1 \\ \mathbf{x} \end{bmatrix}$  be the score for class *l*.

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$$\sum_{l\neq j} h(s_l(\mathbf{x}) - s_j(\mathbf{x}) + \Delta) = \sum_{l\neq j} \max(0, s_l(\mathbf{x}) - s_j(\mathbf{x}) + \Delta),$$

where j is the true label of x and  $\Delta$  contributes a margin ensuring that the true label score has to be at least  $\Delta$  more than the rest to be penalty free

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• Multi-class SVM:

$$\min \lambda \|\mathbf{w}\|^2 + \sum_i \sum_{l \neq j(\mathbf{x}_i)} h(s_l(\mathbf{x}_i) - s_{j(\mathbf{x}_i)}(\mathbf{x}_i) + \Delta)$$

#### Presentation logistics

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- Pick your packages, give me your preference by next Thursday. Include your highest three preferred packages with sorted order

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- The order of presentation is based on popularity of your topic. The most popular topic will be presented first and so on
- Within a topic, the order will be determined randomly

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- Four bonus awards: (5% each) for the best presentation and (3% each) for first runner up according to my taste and popular votes from you all, respectively
- Tentatively reserve Tuesday classes for presentations

#### Software packages

	Pros	Cons
Caffe(2)	Don't need to write code	Adding module is harder
		(need $C++$ ); RNN is not
		support
(Py)Torch	Easy to create own module;	Lua (check out PyTorch)
	Can do RNN	
Theano	Flexible and powerful	Discontinued
Tensorflow	Dominating	Slow in earlier version
		(now?)
Keras /	Less verbose than Theano	Less flexible
Lasagne		
MXnet	Rumored to be fast	Unpopular
Matconvnet	MATLAB	CNN only
CNTK (MS)	?	?
Paddle	?	?
(Baidu)		

Watch this CS231n lecture

S. Cheng (OU-ECE)

#### Final reminder

## Package selection will be due next Thursday