Meta Learning

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University of Oklahoma

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Meta Learning: Learn to learn

- Learn meta-knowledge that shares among tasks
- Often associate with few-shot learning

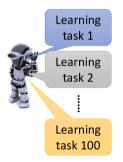


Image credit: Hung-yi Lee

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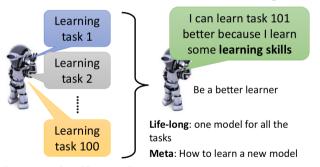


Image credit: Hung-yi Lee

Meta Learning vs Machine Learning

• Machine learning: given input and output, find a function f that maps input to output

$$f(\bigcirc) = \text{``Cat''}$$

Image credit: Hung-Yi Lee

Meta Learning vs Machine Learning

• Machine learning: given input and output, find a function f that maps input to output

$$f(\bigcirc) = \text{"Cat"}$$

• Meta learning: given task training data, find a function F that maps training data to a good ML function f

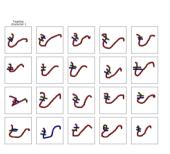
Image credit: Hung-Yi Lee

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MNIST of Meta Learning: Omniglot

- 1623 characters
- 20 examples each
- Github

HXPISOOBULA BURDULA BURDULA BURTHI APPILLA PILLA よう人とですけばはまとなるまなにドレレフとりょうしのとす 3中ののレ そもべ 中山 さいずらめ マアローロー のる かんのひっょっ となく キェングスイスト アナ ののののりとハクトリンをするはずれるのといるのとしょうしょりしいしょりの 囚む囚囚のよう、ロイルで呼ばれて下るととなるはは残し、ロケかながいだい स्टित्हाक्ष ०७४ व क Kig Ebet या ११ म त्य संग्रह ते ८००० ८६ हो रेस् । ४६६ त ४९ ००० ८६ क राष्ट्रक्ष या १६ म त्य स्ग्रह ते ४००० ८६ हो रेस् L S F n E O O P P Y as 20 7 as an E A J E A: :: :: " 4 b Y R K A P X & I LUYNYCOYSTWOLDWASTAMED::: ·· · · bHP4CAY54# α, **、** _ _ _ ¬ Р × + Υ Ν Ο ξ Γ Θ γ = ¬ ¬ « m ~ π π Ο ν ρ l d ປ ປ ປ Σ W X 7 أ ከ n ch x D | * 人名米内今 om come s E c d 4 B n Wyll t U U N つ i 口 V



Other datasets: miniImageNet, CUB

Jargons

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- \bullet N-ways K-shots: N classes and K samples each
- In each task,

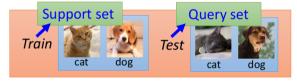
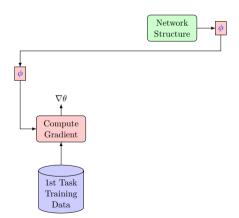


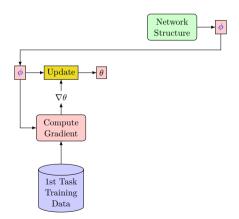
Image credit: Hung-yi Lee

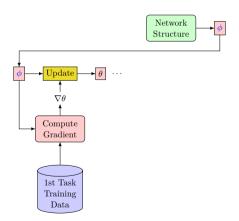
• Focus only on F with same network structure but different initialization ϕ

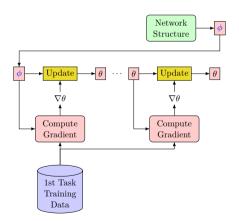
Network Structure

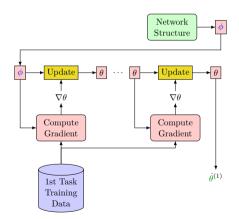


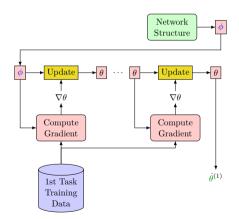


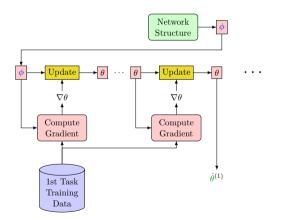


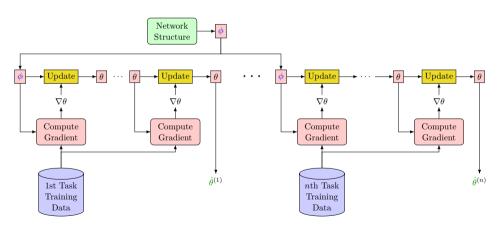




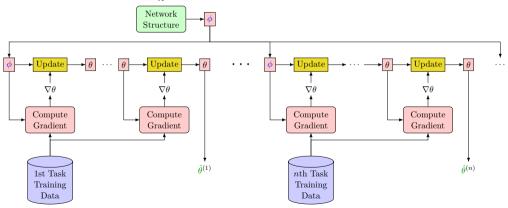




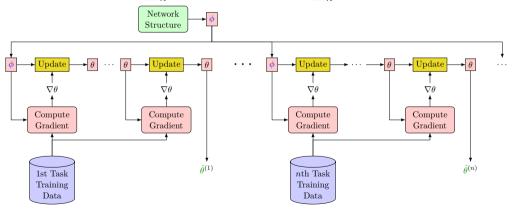




- Focus only on F with same network structure but different initialization ϕ
- Minimize $L(\phi) = \sum_{n} l^{(n)}(\hat{\theta}^{(n)})$



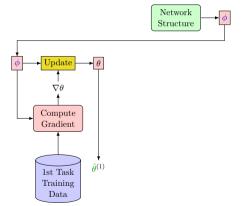
- Focus only on F with same network structure but different initialization ϕ
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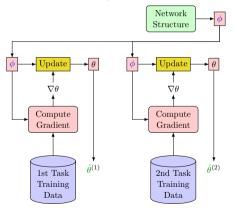
- MAML (Model Agnostic Meta Learning): optimize task θ with only 1 gradient update
- FOMAML (First Order MAML): 1st order approximation. Get rid of 2nd order terms



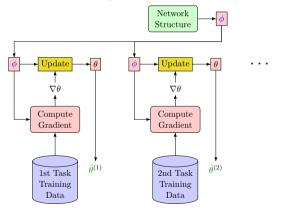
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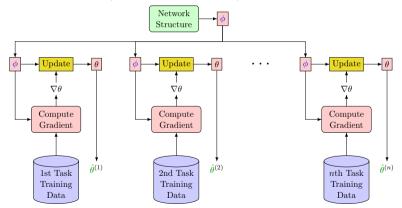
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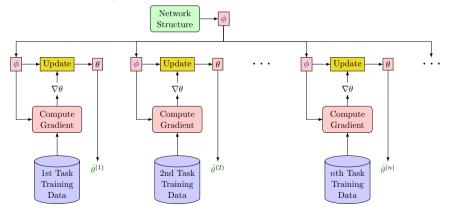
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MAML

Model Pre-training



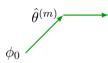
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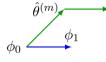
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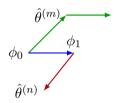


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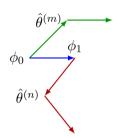
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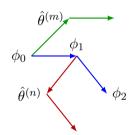
 \longrightarrow : sample from Task m

MAML



 \rightarrow : sample from Task m \rightarrow : sample from Task n

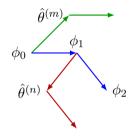
MAML



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MAML

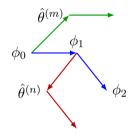


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MAML

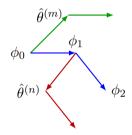


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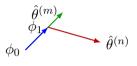


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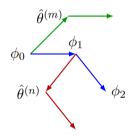


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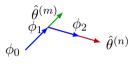


MAML



 \longrightarrow : sample from Task m

 \longrightarrow : sample from Task n



MAML vs Pre-training

MAML optimizes the potential of ϕ : $L(\phi) = \sum_{n} l^{(n)}(\hat{\theta}^{(n)})$

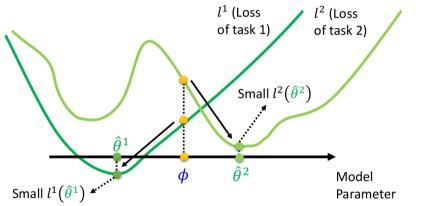


Image credit: Hung-yi Lee

MAML vs Pre-training

Pre-training optimizes the current ϕ for all tasks: $L(\phi) = \sum_{n} l^{(n)}(\phi)$

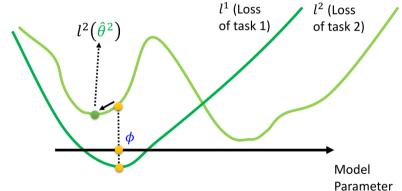


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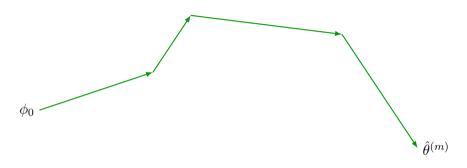


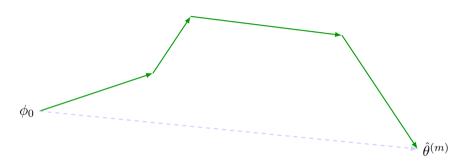


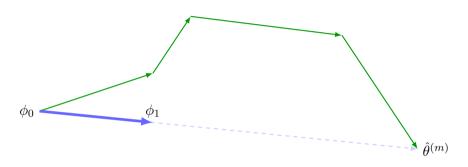


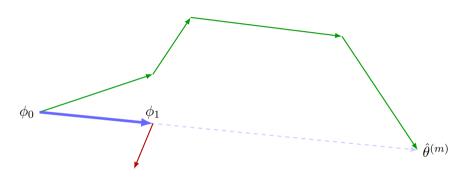




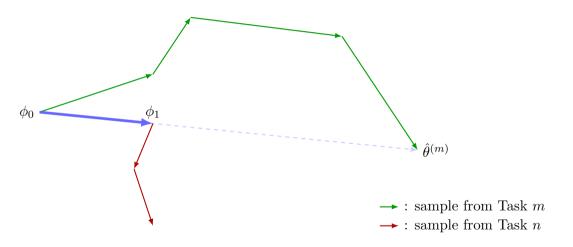


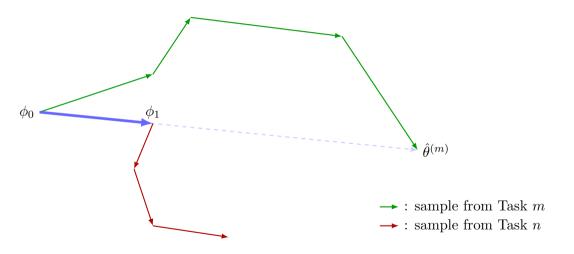


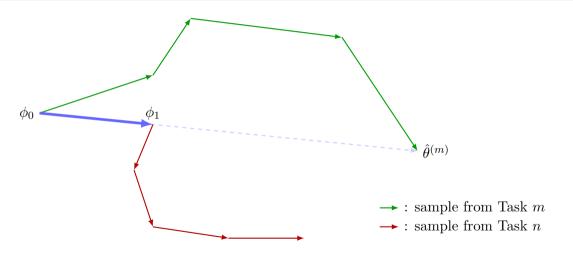


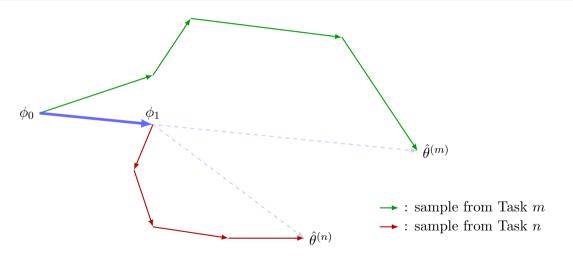


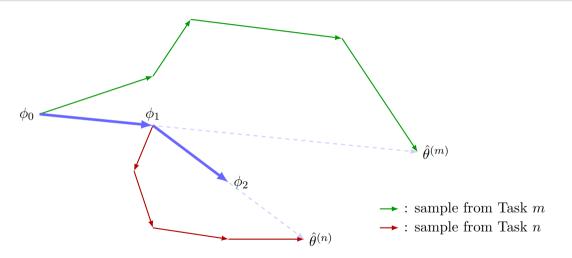
 \longrightarrow : sample from Task m











Reptile Result

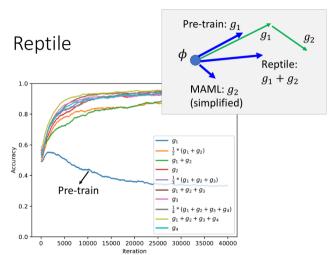


Image credit: Hung-yi Lee

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$$\frac{\partial \theta_i}{\partial \phi_j} = \frac{\partial \phi_i}{\partial \phi_j} - \frac{1}{\lambda} \sum_k \frac{\partial^2 l^{(\tau)}}{\partial \theta_k \partial \theta_i} \frac{\partial \theta_k}{\partial \phi_j}$$

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Thus, the meta-gradient (from task τ) is

$$\nabla_{\phi} l^{(\tau)}(\theta) = \frac{d\theta}{d\phi} \nabla_{\theta} l^{(\tau)}(\theta)$$



iMAML: Implicit Gradient

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This involves inverting n^2 -size matrix, which is infeasible to compute directly. Consider instead

$$\underbrace{\left(I + \frac{H(l^{(\tau)}(\theta))}{\lambda}\right)}_{A}g = \underbrace{\nabla_{\theta}l^{(\tau)}(\theta)}_{b},$$

which can be solved using conjugate gradient method

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 - Here we use the bracket notation commonly used in physics, $p^{\top}q = \langle p, q \rangle$ and $p^{\top}Aq = \langle p, Aq \rangle = \langle pAq \rangle$



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 - Here we use the bracket notation commonly used in physics, $p^{\top}q = \langle p, q \rangle$ and $p^{\top}Aq = \langle p, Aq \rangle = \langle pAq \rangle$
- If we can keep generating conjugate directions p_k , we can find the solution x that satisfies Ax = b by simply computing $\alpha_i = \frac{\langle p_i, b Ax_0 \rangle}{\langle p_i, Ap_i \rangle}$



Consider an initial guess x_0 for the problem Ax = b. And iterate as follow

$$r_0 = Ax_0 - b,$$
 $p_0 = -r_0,$ $x_1 = x_0 + \alpha_0 p_0$ (1)

$$r_1 = Ax_1 - b,$$
 $p_1 = -r_1 + \beta_0 p_0,$ $x_2 = x_1 + \alpha_1 p_1$ (2)

$$r_2 = Ax_2 - b,$$
 $p_2 = -r_2 + \beta_1 p_1,$ $x_3 = x_2 + \alpha_2 p_2$ (3)

. . .

• From the middle equations, $\{p_0, p_1, \dots, p_n\}$ and $\{r_0, r_1, \dots, r_n\}$ span the same space

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- From the middle equations, $\{p_0, p_1, \dots, p_n\}$ and $\{r_0, r_1, \dots, r_n\}$ span the same space
- $r_k = Ax_{k-1} + \alpha_{k-1}Ap_{k-1} b$



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- From the middle equations, $\{p_0, p_1, \dots, p_n\}$ and $\{r_0, r_1, \dots, r_n\}$ span the same space
- $r_k = Ax_{k-2} + \alpha_{k-2}Ap_{k-2} + \alpha_{k-1}Ap_{k-1} b$

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. . .

•
$$r_k = Ax_0 + \alpha_0 Ap_0 + \alpha_1 Ap_1 + \dots + \alpha_{k-1} Ap_{k-1} - b$$

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- $r_k = -p_0 + \alpha_0 A p_0 + \alpha_1 A p_1 + \dots + \alpha_{k-1} A p_{k-1}$.
- $Ap_k \in \text{span}\{p_0, p_1, \dots, p_{k+1}\} \text{ for } k \ge 0.$



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- $r_k = -p_0 + \alpha_0 A p_0 + \alpha_1 A p_1 + \dots + \alpha_{k-1} A p_{k-1}$.
- $Ap_k \in \operatorname{span}\{p_0, p_1, \cdots, p_{k+1}\}\$ for $k \geq 0$. We can show that with induction
 - For k = 0, $p_1 = -r_1 + \beta_0 p_0$



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- From the middle equations, $\{p_0, p_1, \dots, p_n\}$ and $\{r_0, r_1, \dots, r_n\}$ span the same space
- $r_k = -p_0 + \alpha_0 A p_0 + \alpha_1 A p_1 + \dots + \alpha_{k-1} A p_{k-1}$.
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 - For k = 0, $p_1 = p_0 \alpha_0 A p_0 + \beta_0 p_0 \Rightarrow A p_0 = \frac{1}{\alpha_0} [p_0 + \beta_0 p_0 p_1] \in \operatorname{span}\{p_0, p_1\}$

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 - For k = 0, $p_1 = p_0 \alpha_0 A p_0 + \beta_0 p_0 \Rightarrow A p_0 = \frac{1}{\alpha_0} [p_0 + \beta_0 p_0 p_1] \in \text{span}\{p_0, p_1\}$
 - Assume $Ap_{k-1} \in \operatorname{span}\{p_0, p_1, \cdots, p_k\},\$



Consider an initial guess x_0 for the problem Ax = b. And iterate as follow

$$r_0 = Ax_0 - b,$$
 $p_0 = -r_0,$ $x_1 = x_0 + \alpha_0 p_0$ (1)

$$r_1 = Ax_1 - b,$$
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$$r_2 = Ax_2 - b,$$
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- From the middle equations, $\{p_0, p_1, \dots, p_n\}$ and $\{r_0, r_1, \dots, r_n\}$ span the same space
- $r_k = -p_0 + \alpha_0 A p_0 + \alpha_1 A p_1 + \dots + \alpha_{k-1} A p_{k-1}$.
- $Ap_k \in \text{span}\{p_0, p_1, \dots, p_{k+1}\}\$ for $k \geq 0$. We can show that with induction
 - For k = 0, $p_1 = p_0 \alpha_0 A p_0 + \beta_0 p_0 \Rightarrow A p_0 = \frac{1}{\alpha_0} [p_0 + \beta_0 p_0 p_1] \in \text{span}\{p_0, p_1\}$
 - Assume $Ap_{k-1} \in \text{span}\{p_0, p_1, \dots, p_k\}, p_{k+1} = -r_{k+1} + \beta_k p_k$

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where
$$\alpha_n = \frac{\langle p_n, b - Ax_0 \rangle}{\langle p_n Ap_n \rangle} = \frac{\langle p_n, p_0 \rangle}{\langle p_n Ap_n \rangle}$$
 and $\beta_n = \frac{\langle r_{n+1} Ap_n \rangle}{\langle p_n Ap_n \rangle}$



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• From the choice of α_n , we see that $r_n \to 0$ and $x_n \to x$ as long as $p_i \perp_A p_j, i \neq j$



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 $p_2 = -r_2 + \beta_1 p_1,$ $x_3 = x_2 + \alpha_2 p_2$ (3)

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- From the choice of α_n , we see that $r_n \to 0$ and $x_n \to x$ as long as $p_i \perp_A p_j, i \neq j$
- We will show that in the next several slides with induction, note that we also have $p_i \perp r_j$ for i < j. It is convenient to show them together

Consider an initial guess x_0 for the problem Ax = b. And iterate as follow

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• From the choice of β , we have $\langle p_{k+1}Ap_k \rangle = \langle -r_{k+1} + \beta_k p_k, Ap_k \rangle$



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• From the choice of β , we have $\langle p_{k+1}Ap_k\rangle = \langle -r_{k+1} + \frac{\langle r_{k+1}Ap_k\rangle}{\langle p_kAp_k\rangle}p_k, Ap_k\rangle = 0$



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where $\alpha_n = \frac{\langle p_n, b - Ax_0 \rangle}{\langle p_n Ap_n \rangle} = \frac{\langle p_n, p_0 \rangle}{\langle p_n Ap_n \rangle}$, $\beta_n = \frac{\langle r_{n+1} Ap_n \rangle}{\langle p_n Ap_n \rangle}$ and $r_k = -p_0 + \alpha_0 Ap_0 + \alpha_1 Ap_1 + \cdots + \alpha_{k-1} Ap_{k-1}$

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• From the choice of β , we have $\langle p_{k+1}Ap_k\rangle = \langle -r_{k+1}+p_k,Ap_k\rangle = 0 \Rightarrow p_{k+1}\perp_A p_k$. In particular, $p_1\perp_A p_0$



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- From the choice of β , we have $\langle p_{k+1}Ap_k \rangle = \langle -r_{k+1} + p_k, Ap_k \rangle = 0 \Rightarrow p_{k+1} \perp_A p_k$. In particular, $p_1 \perp_A p_0$
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- And $\langle p_0, r_1 \rangle = \langle p_0, p_0 \frac{\langle p_0, p_0 \rangle}{\langle p_0, Ap_0 \rangle} Ap_0 \rangle = 0$. Thus, $p_0 \perp r_1$



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• For $i < j \le k$, assume that we have $p_i \perp_A p_j$ and $p_i \perp r_j$

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- For $i < j \le k$, assume that we have $p_i \perp_A p_j$ and $p_i \perp r_j$
- For i < j = k + 1,
 - $\bullet \langle p_i, r_{k+1} \rangle = \langle p_i, -p_0 + \alpha_0 A p_0 + \dots + \alpha_k A p_k \rangle$



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- For i < j = k + 1,
 - $\langle p_i, r_{k+1} \rangle = 0$
 - Assume i < k as $p_k \perp_A p_{k+1}$ was already shown



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- For i < j = k + 1,

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where $\alpha_n = \frac{\langle p_n, b - Ax_0 \rangle}{\langle p_n Ap_n \rangle} = \frac{\langle p_n, p_0 \rangle}{\langle p_n Ap_n \rangle}$, $\beta_n = \frac{\langle r_{n+1} Ap_n \rangle}{\langle p_n Ap_n \rangle}$ and $r_k = -p_0 + \alpha_0 Ap_0 + \alpha_1 Ap_1 + \cdots + \alpha_{k-1} Ap_{k-1}$

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$$r_1 = Ax_1 - b,$$
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- For i < j = k + 1, $(Ap_i \in \text{span}\{p_0, p_1, \dots, p_{i+1}\})$
 - $\langle p_i, r_{k+1} \rangle = 0$
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$$p_{k+1} = -r_{k+1} - \beta_k r_k - \beta_k \beta_{k-1} r_{k-1} - \dots - \beta_k \beta_{k-1} \dots \beta_{i+1} r_{i+1} + \beta_k \beta_{k-1} \dots \beta_i p_i$$

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• Thus, by induction, $p_i \perp_A p_j$ (and $p_i \perp r_j$) for all i < j

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- Given initial $x = x_0$, the gradient is $Ax_0 b \propto p_0$. The remaining search directions are all conjugate to p_0 . Thus the name conjugate gradient
- There is no need to actually compute the Hessian, the update only involves Hessian-vector product Hv, we can compute

$$Hv = \frac{d}{dt}\Big|_{t=0} \nabla f(x+tv)$$



Samuel Cheng (University of Oklahoma)

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 - Model-based approach: design network that avoids overfitting



Reference

- Hung-yi Lee's MAML lecture
- An Interactive Introduction to Model-Agnostic Meta-Learning