Information Theory and Probabilistic Programming

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October 10, 2019

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An optimization example

- Simple economy: *m* prosumers, *n* different goods¹
- Each individual: production $\mathbf{p}_i \in \mathbb{R}_n$, consumption $\mathbf{c}_i \in \mathbb{R}_n$
- Expense of producing " \mathbf{p} " for agent $i = e_i(\mathbf{p})$
- Utility (happiness) of consuming "c" units for agent $i = u_i(\mathbf{c})$
- Maximize happiness

$$\max_{\mathbf{p}_i,\mathbf{c}_i}\sum_{i=1}^m (u_i(\mathbf{c}_i)-e_i(\mathbf{p}_i)) \qquad s.t. \qquad \sum_{i=1}^m \mathbf{c}_i=\sum_{i=1}^m \mathbf{p}_i$$

¹Example borrowed from the first lecture of Prof Gordon's CMU CS $_10-725$ = \sim \sim

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Walrasian equilibrium

$$\max_{\mathbf{p}_i,\mathbf{c}_i}\sum_{i=1}^m (u_i(\mathbf{c}_i) - e_i(\mathbf{p}_i)) \qquad s.t. \qquad \sum_{i=1}^m \mathbf{c}_i = \sum_{i=1}^m \mathbf{p}_i$$

• Idea: introduce price λ_i to each good j. Let the market decide

- Price $\lambda_j \uparrow$: consumption of good $j \downarrow$, production of good $j \uparrow$
- Price $\lambda_j \downarrow$: consumption of good $j \uparrow$, production of good $j \downarrow$
- Can adjust price until consumption = production for each good

Algorithm: tâtonnement

Assume that the appropriate prices are found, we can ignore the equality constraint, then the problem becomes

$$\max_{\mathbf{p}_i,\mathbf{c}_i}\sum_{i=1}^m (u_i(\mathbf{c}_i) - e_i(\mathbf{p}_i)) \quad \Rightarrow \quad \sum_{i=1}^m \max_{\mathbf{p}_i,\mathbf{c}_i} (u_i(\mathbf{c}_i) - e_i(\mathbf{p}_i))$$

So we can simply optimize production and consumption of each individual independently

Algorithm 1 tâtonnement

- 1: procedure FINDBESTPRICES
- 2: $\lambda \leftarrow [0, 0, \cdots, 0]$
- 3: **for** $k = 1, 2, \cdots$ **do**
- 4: Each individual solves for its c_i and p_i for the given λ
- 5: $\lambda \leftarrow \lambda + \delta_k \sum_i (c_i p_i)$

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Lagrange multiplier

Problem

$$\max_{\mathbf{x}} f(\mathbf{x})$$
$$g(\mathbf{x}) = 0$$

Consider $L(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$ and let $\tilde{f}(\mathbf{x}) = \min_{\lambda} L(\mathbf{x}, \lambda)$.

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Therefore, the problem is identical to $\max_{\mathbf{x}} \tilde{f}(\mathbf{x})$ or

$$\max_{\mathbf{x}} \min_{\lambda} (f(\mathbf{x}) - \lambda g(\mathbf{x})),$$

where λ is known to be the Lagrange multiplier.

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Lagrange multiplier (con't)

Assume the optimum is a saddle point,

$$\max_{\mathbf{x}} \min_{\lambda} (f(\mathbf{x}) - \lambda g(\mathbf{x})) = \min_{\lambda} \max_{\mathbf{x}} (f(\mathbf{x}) - \lambda g(\mathbf{x})),$$

the R.H.S. implies

 $\nabla f(\mathbf{x}) = \lambda \nabla g(\mathbf{x})$

Inequality constraint

Problem

$$\max_{\mathbf{x}} f(\mathbf{x})$$
$$g(\mathbf{x}) \leq 0$$

Consider $\tilde{f}(\mathbf{x}) = \min_{\lambda \geq 0} (f(\mathbf{x}) - \lambda g(\mathbf{x}))$,

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Therefore, we can rewrite the problem as

$$\max_{\mathbf{x}} \min_{\lambda \geq 0} (f(\mathbf{x}) - \lambda g(\mathbf{x}))$$

Inequality constraint (con't)

Assume

$$\max_{\mathbf{x}} \min_{\lambda \ge 0} (f(\mathbf{x}) - \lambda g(\mathbf{x})) = \min_{\lambda \ge 0} \max_{\mathbf{x}} (f(\mathbf{x}) - \lambda g(\mathbf{x}))$$

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The R.H.S. implies

$$abla f(\mathbf{x}) = \lambda
abla g(\mathbf{x})$$

Moreover, at the optimum point $(\mathbf{x}^*, \lambda^*)$, we should have the so-called "complementary slackness" condition

$$\lambda^* g(\mathbf{x}^*) = 0$$

since

$$\max_{\substack{\mathbf{x} \\ g(\mathbf{x}) \leq 0}} f(\mathbf{x}) \equiv \max_{\substack{\mathbf{x} \\ \lambda \geq 0}} \min(f(\mathbf{x}) - \lambda g(\mathbf{x}))$$

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Karush-Kuhn-Tucker conditions

Problem

$$\begin{split} \max_{\mathbf{x}} f(\mathbf{x}) \\ g(\mathbf{x}) \leq 0, \quad h(\mathbf{x}) = 0 \end{split}$$

Conditions

$$egin{aligned}
abla f(\mathbf{x}^*) &- \mu^*
abla g(\mathbf{x}^*) - \lambda^*
abla h(\mathbf{x}^*) &= 0 \ g(\mathbf{x}^*) &\leq 0 \ h(\mathbf{x}^*) &= 0 \ \mu^* &\geq 0 \ \mu^* g(\mathbf{x}^*) &= 0 \end{aligned}$$

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- However, we want to make sure that we can losslessly decode the message also!

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 - We say $c(\mathbf{x})$ is uniquely decodable if all input sequences map to different outputs

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- Instead, for a mapping $a \mapsto 1, b \mapsto 01, c \mapsto 001, d \mapsto 0001$, I will argue that we can always decode a symbol "once it is available"
 - Note that the catch is that there is no codeword being the "prefix" of another codeword
 - We call such code a prefix-free code or an instantaneous code

Kraft's Inequality

- How do we know if a length profile for a code is possible?
- Kraft's inequality: Consider a length profile l_1, l_2, \dots, l_K , there exists a uniquely decodable code for symbols x_1, x_2, \dots, x_K such that $l(x_1) = l_1, l(x_2) = l_2, \dots, l(x_K) = l_K$ if and only if $\sum_{k=1}^K 2^{-l_k} \le 1$

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Intuition

Consider # "descendants" of each codeword at the " I_{max} "-level, then for prefix-free code, we have

$$\sum_{k=1}^{K} 2^{l_{max}-l} \leq 2^{l_{max}}$$

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Given l_1, l_2, \dots, l_K satisfy $\sum_{k=1}^{K} 2^{-l_k} \leq 1$, we can assign nodes on a tree as previous slides. More precisely,

- Assign *i*-th node as a node at level *l_i*, then cross out all its descendants
- Repeat the procedure for *i* from 1 to K
- We know that there are sufficient tree nodes to be assigned since the Kraft's inequaltiy is satisfied

The corresponding code is apparently prefix-free and thus is uniquely decodable

Consider message from coding k symbols $\mathbf{x} = x_1, x_2, \cdots, x_k$

$$\left(\sum_{x\in\mathcal{X}} 2^{-l(x)}\right)^k = \left(\sum_{x_1\in\mathcal{X}} 2^{-l(x_1)}\right) \left(\sum_{x_2\in\mathcal{X}} 2^{-l(x_2)}\right) \cdots \left(\sum_{x_k\in\mathcal{X}} 2^{-l(x_k)}\right)$$
$$= \sum_{x_1,x_2,\cdots,x_k\in\mathcal{X}^k} 2^{-(l(x_1)+l(x_2)+\cdots+l(x_k))}$$

$$=\sum_{\mathbf{x}\in\mathcal{X}^k}2^{-l(\mathbf{x})}$$

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Consider message from coding k symbols $\mathbf{x} = x_1, x_2, \cdots, x_k$

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where a(m) is the number of codeword with length m. However, for the code to be uniquely decodable, $a(m) \leq 2^m$, where 2^m is the number of available codewords with length m.

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$$\sum_{x \in \mathcal{X}} 2^{-l(x)} \leq (k l_{max})^{1/k}$$

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$$\sum_{x\in\mathcal{X}}2^{-l(x)}\leq (kl_{max})^{1/k}pprox 1$$
 as $k
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$$\begin{split} \min_{l_1, l_2, \cdots, l_K} \sum_{k=1}^K p_k l_k \text{ subject to } \sum_{k=1}^K 2^{-l_k} \leq 1 \text{ and } l_1, \cdots, l_K \geq 0 \\ \equiv \max_{l_1, l_2, \cdots, l_K} - \sum_{k=1}^K p_k l_k \text{ subject to } \sum_{k=1}^K 2^{-l_k} - 1 \leq 0 \text{ and } -l_1, \cdots, -l_K \leq 0 \end{split}$$

KKT conditions

$$-\nabla\left(\sum_{k=1}^{K}p_{k}l_{k}\right)-\mu_{0}\nabla\left(\sum_{k=1}^{K}2^{-l_{k}}-1\right)+\sum_{k=1}^{K}\mu_{k}\nabla l_{k}=0$$

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$$\mu_0\left(\sum_{k=1}^{K} 2^{-l_k} - 1\right) = 0, \quad \mu_k l_k = 0$$

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$$\sum_{k=1}^{K} \frac{p_j}{\mu_0 \log 2} = \frac{1}{\mu_0 \log 2} \le 1 \Rightarrow \mu_0 \ge \frac{1}{\log 2}$$

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Note that as $\mu_0 \downarrow$, $\frac{p_j}{\mu_0 \log 2} \uparrow$ and $l_j \downarrow$. Therefore, if we want to decrease code rate, we should reduce μ_0 as much as possible. Thus, take $\mu_0 = \frac{1}{\log 2}$. Then $2^{-l_j} = p_j \Rightarrow l_j = -\log_2 p_j$. Thus, the minimum rate becomes

$$\sum_{k=1}^{K} p_k l_k = -\sum_{k=1}^{K} p_k \log_2 p_k \triangleq H(p_1, \cdots, p_K)$$

Review

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 - We cannot compress a source losslessly below its entropy
 - On the other hand, since Kraft's inequality guarantee existence of code, we should be able to find code to achieve the theoretical limit
- However, the proof we discussed was not constructive. How can we actually design a code to compress arbitrarily close to the theoretical limit?

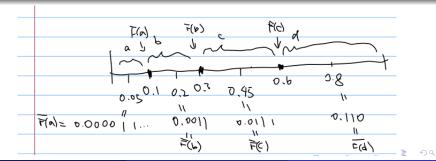
Shannon-Fano-Elias code

Key idea

Each codeword corresponds to an intervel of [0,1]

Example

110 corresponds to [0.110, 0.1101] = [0.11, 0.111) = [0.75, 0.875)



S. Cheng (OU-ECE)

Information Theory and Probabilistic Progra

Shannon-Fano-Elias code

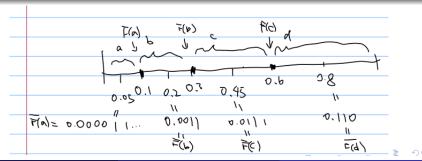
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Information Theory and Probabilistic Progra

Observations

Remark (Observation 1)

Let l(x) = |c(x)| be the length of the SFE codeword, and let u(x) be the corresponding interval. Then, the length of the interval $|u(x)| = 2^{-l(x)}$

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Proof of Observation 2.

 $A \Rightarrow B \equiv \neg B \Rightarrow \neg A$. We will show instead if $c(x_1)$ and $c(x_2)$ are prefix of one another, then $u(x_1)$ and $u(x_2)$ overlap. WLOG, assume $c(x_1)$ is a prefix of $c(x_2)$, the lower boundary of $u(x_1)$ is below the lower boundary of $u(x_2)$ and yet the upper boundary of $u(x_1)$ is above the upper boundary of $u(x_2)$. Thus, $u(x_2) \subseteq u(x_1)$ and hence $u(x_1)$ and $u(x_2)$ overlap each other

Consider a source that

$$p(x_1) = 0.25, p(x_2) = 0.25, p(x_3) = 0.2, p(x_4) = 0.15, p(x_5) = 0.15$$

x	p(x)	F(x)	$\overline{F}(x)$	$\overline{F}(x)$ in Binary	$l(x) = \left\lceil \log \frac{1}{p(x)} \right\rceil + 1$	Codeword
1	0.25	0.25	0.125	0.001	3	001
2	0.25	0.5	0.375	0.011	3	011
3	0.2	0.7	0.6	0.10011	4	1001
4	0.15	0.85	0.775	0.1100011	4	1100
5	0.15	1.0	0.925	$0.111\overline{0110}$	4	1110

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- Average code rate is upper bounded by H(X) + 2

$$\sum_{x \in \mathcal{X}} p(x)I(x) = \sum_{x \in \mathcal{X}} p(x) \left(\left\lceil \log_2 \frac{1}{p(x)} \right\rceil + 1 \right)$$
$$\leq \sum_{x \in \mathcal{X}} p(x) \left(\log_2 \frac{1}{p(x)} + 2 \right) = H(X) + 2$$

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= $2H(X)$

Therefore, the code rate per original symbol is upper bounded by

$$\frac{1}{2}(H(X_{5})+2) = H(X)+1$$

Forward proof of Source Coding Theorem

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Therefore as long as a given rate R > H(X), we can always find a large enough N such that the code rate using the "grouping trick" and SFE code is below R. This concludes the forward proof

Von Neumman to Shannon

"You should call it entropy for two reasons: first because that is what the formula is in statistical mechanics but second and more important, as nobody knows what entropy is, whenever you use the term you will always be at an advantage!" -John von Neumman

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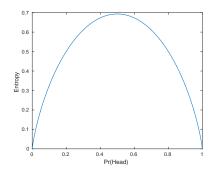
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- A less likely event has "more" information and requires more bits to store. H(X) is just the average number of bits required

Biased coin with Pr(Head) = p

$$H(X) = -Pr(Head) \log Pr(Head) - Pr(Tail) \log Pr(Tail)$$
$$= -p \log p - (1-p) \log(1-p)$$

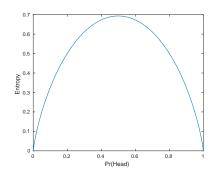
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- Entropy is 0 when p = 0 or p = 1
- Entropy can be interpreted as the average uncertainty of the outcome or the amount of information "gained" after the outcome is revealed



Differential entropy

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The definition makes little sense for a continuous X. Since the probability of an outcome x is always 0, we may define instead the differential entropy for X as

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Uniform Distribution

If
$$p(X) = \begin{cases} 1/a & 0 \le x \le a \\ 0 & \text{otherwise} \end{cases}$$

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N.B. h(X) only depends on σ^2 and is independent of μ as one would expect

For N-dim multivariate normal distributed $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$,

$$\begin{split} h(\mathbf{X}) &= E[-\log p(\mathbf{X})] \\ &= -E\left[\log\left(\frac{1}{\sqrt{\det\left(2\pi\Sigma\right)}}\exp\left(-\frac{1}{2}(\mathbf{X}-\boldsymbol{\mu})^{T}\Sigma^{-1}(\mathbf{X}-\boldsymbol{\mu})\right)\right)\right] \end{split}$$

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$$= \log\sqrt{\det(2\pi\Sigma)} + \frac{N\log e}{2} = \log\sqrt{e^{N}\det(2\pi\Sigma)} = \log\sqrt{\det(2\pi\epsilon\Sigma)}$$

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How differential entropy is related to its discrete counterpart?

- Consider a continuous random variable X
- Let X^{Δ} is a "quantized" version of it with quantization stepsize of Δ

$$H(X^{\Delta}) = \sum -p_{X^{\Delta}}(x^{\Delta}) \log p_{X^{\Delta}}(x^{\Delta})$$

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$$= h(X) - \log \Delta$$

Answer

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- If we want to store with precision of 0.01 ms, we need $h(T) \log 0.01 \approx 7.64 bits$

Lower bound of entropy

$H(X) \geq 0$

Since $p(X) \leq 1$, $-\log p(X) \geq 0$, therefore $H(X) = E[-\log p(X)] \geq 0$

After all, H(X) represents the required bits to compress the source X

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Caveat

It does NOT need to be true for differential entropy. It is possible that h(X) < 0

For example, for a uniformly distributed X from 0 to 0.5, $h(X) = \log 0.5 = -1$

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Jensen's Inequality

For a convex (bowl-shape) function f

 $E[f(X)] \ge f(E[X])$

convex function

Jensen's Inequality





convex function

Let us consider X with only two outcomes x_1 and x_2 with probabilities p and 1 - p. Easy to see that

 $E[f(X)] \ge f(E[X])$

$$E[f(X)] = pf(x_1) + (1-p)f(x_2) \ge f(px_1 + (1-p)x_2) = f(E[X])$$

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Result can be extended to variables with more than two outcomes easily

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Examples

You should know this bound long alone. Think of the maximum number of bits needed:

- to store the outcome of flipping a coin: $\log 2 = 1$ bit
- to store the outcome of throwing a dice: $\log 6 \le 3$ bits

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Review

• Source coding theorem: For an independent and identically distributed (i.i.d.) discrete memoryless source (DMS) X, we can always compress it with no less than H(X) bits per input symbol, where $H(X) = -\sum_{x \in \mathcal{X}} p(x) \log p(x) = E[-\log p(X)]$

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- For a quantized version of continuous X, $H(X_{\Delta}) = h(X) \log \Delta$
- For multivariate normal $oldsymbol{X} \sim \mathcal{N}(oldsymbol{\mu}, \Sigma)$,

$$h(\boldsymbol{X}) = \log \sqrt{\det (2\pi e \Sigma)}$$

Lecture 5

Upper bound of differential entropy

$$h(X) \leq \log E\left[\frac{1}{p(X)}\right] = \log \int_{x \in \mathcal{X}} p(x) \frac{1}{p(x)} dx = \log |\mathcal{X}|$$

• The expression still makes sense but it is not useful usually since the sampling space can be unbounded $|\mathcal{X}| = \infty$ (for example, normally distributed X)

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- The expression still makes sense but it is not useful usually since the sampling space can be unbounded $|\mathcal{X}| = \infty$ (for example, normally distributed X)
- Thus it makes much more sense to consider upper bound of a differential entropy constrained on the variance of the variable (why not constrained on mean?)
- It turns out that for a fixed variance σ^2 , the variable will have largest differential entropy if it is normally distributed (will show later). Thus

$$h(X) \leq \log \sqrt{2\pi e \sigma^2}$$

Joint entropy

For multivariate random variable, we can extend the definition of entropy naturally as follows:

Entropy

$$H(X,Y) = E[-\log p(X,Y)]$$

and

$$H(X_1, X_2, \cdots, X_N) = E[-\log p(X_1, \cdots, X_N)]$$

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Conditional entropy

$$H(X, Y) = E[-\log p(X, Y)] = E[-\log p(X) - \log p(Y|X)]$$
$$= H(X) + \underbrace{E[-\log p(Y|X)]}_{H(Y|X)}$$

Entropy

$$H(Y|X) \triangleq H(X, Y) - H(X)$$

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Interpretation

Total Info. of X and Y = Info. of X + Info. of Y knowing X

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$H(Y|X) = E[-\log p(Y|X)]$

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= $\sum_{x} p(x) \sum_{y} -p(y|x) \log p(y|x)$
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The conditional entropy H(Y|X) is essentially the average of H(Y|x) over all possible value of x

Chain rule

Entropy

$$H(X_1, X_2, \cdots, X_N) = H(X_1) + H(X_2|X_1) + H(X_3|X_1, X_2) + \cdots + H(X_N|X_1, X_2, \cdots, X_{N-1}).$$

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Example

Pr(Rain, With umbrella) = 0.2 Pr(Rain, No umbrella) = 0.1Pr(Sunny, With umbrella) = 0.2 Pr(Sunny, No umbrella) = 0.5

 $W \in \{Rain, Sunny\}$ $U \in \{With umbrella, No umbrella\}$

Entropies

$$\begin{split} H(W, U) &= -0.2 \log 0.2 - 0.1 \log 0.1 - 0.2 \log 0.2 - 0.5 \log 0.5 = 1.76 \text{ bits} \\ H(W) &= -0.3 \log 0.3 - 0.7 \log 0.7 = 0.88 \text{ bits} \\ H(U) &= -0.4 \log 0.4 - 0.6 \log 0.6 = 0.97 \text{ bits} \\ H(W|U) &= H(W, U) - H(U) = 0.79 \text{ bits} \\ H(U|W) &= H(W, U) - H(W) = 0.88 \text{ bits} \end{split}$$

It is often useful to gauge the difference between two distributions. KL-divergence is also known to be relative entropy. It is a way to measure the difference between two distributions. For two distributions of X, p(x) and p(y),

$$\mathcal{KL}(p(x)\|q(x)) riangleq \sum_{x \in \mathcal{X}} p(x) \log_2 rac{p(x)}{q(x)}.$$

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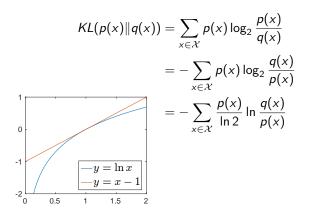
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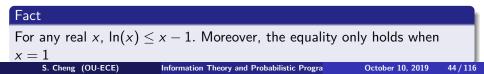
• N.B. $KL(p(x)||q(x)) \neq KL(q(x)||p(x))$ in general

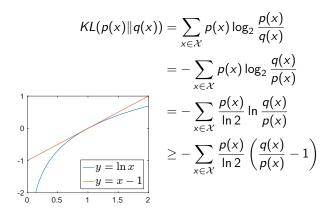
$$\begin{aligned} \mathsf{KL}(p(x) \| q(x)) &= \sum_{x \in \mathcal{X}} p(x) \log_2 \frac{p(x)}{q(x)} \\ &= -\sum_{x \in \mathcal{X}} p(x) \log_2 \frac{q(x)}{p(x)} \end{aligned}$$

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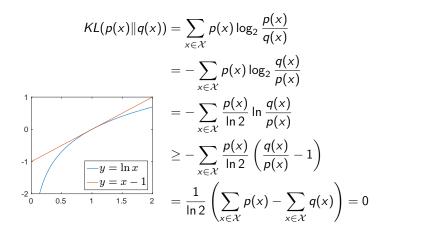
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For any real x, $\ln(x) \le x - 1$. Moreover, the equality only holds when x = 1S. Cheng (OU-ECE) Information Theory and Probabilistic Progra October 10, 2019 44/116



Fact

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Continuous variables

We can define KL-divergence for continuous variables in a similar manner

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For fixed variance (covariance matrix), normal distribution has highest entropy

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$$0 \leq \mathsf{KL}(f \| \phi) = \int_{\mathbf{x}} f(\mathbf{x}) \log \frac{f(\mathbf{x})}{\phi(\mathbf{x})} d\mathbf{x} = -h(f) - \int_{\mathbf{x}} f(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x}$$

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$$= -h(f) - \int_{\mathbf{x}} \phi(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x} = -h(f) + h(\phi)$$

 $\int_{\mathbf{x}} f(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x} = \int_{\mathbf{x}} \phi(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x}$

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$\int_{\mathbf{x}} f(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x} = \int_{\mathbf{x}} \phi(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x}$

$$\int_{\mathbf{x}} \phi(\mathbf{x}) \log \phi(\mathbf{x}) d\mathbf{x} = \int_{\mathbf{x}} \phi(\mathbf{x}) \left[-\log \sqrt{\det(2\pi\Sigma)} - \frac{1}{2} \mathbf{x}^T \Sigma^{-1} \mathbf{x} \right] d\mathbf{x}$$
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Application: Thiel index

- Measure economic inequality among different groups or for a group of individuals
- Let p_i be the economic wealth proportion of group i, and q_i be the population size proportion of group i
- Thiel index is simply KL(p||q)
- Let's apply to a group of N individuals.
 - If they all have the same wealth, both p and q are uniform $(p_i = q_i = 1/N)$, thus Thiel index = KL(p||q) = 0
 - If one of them own everything, q is uniform but p is a δ -function. Thus Thiel index = $KL(p||q) = \sum_{i} p_i \log \frac{p_i}{q_i} = \log \frac{1}{1/N} = \log N$

In machine learning, it is often needed to assess the quality of a trained system. Consider the example of classifying an the political affliation of an individual

computed targets	correct?	computed targets	correct?
0.3 0.3 0.4 0 0 1 (democrat) 0.3 0.4 0.3 0 1 0 (republican) 0.1 0.2 0.7 1 0 0 (other)		0.1 0.2 0.7 0 0 1 (democrat) 0.1 0.7 0.2 0 1 0 (republican) 0.3 0.4 0.3 1 0 0 (other)	

In a first glance, both examples appear to work equally well (or bad). Both have one classification error. However, a closer look will suggest the prediction of LHS is worse than RHS (why?)

(https://jamesmccaffrey.wordpress.com/2013/11/05/why-you-should-use-cross-entropy-error-instead-of-classification-error-ormean-squared-error-for-neural-network-classifier-training/)

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In a first glance, both examples appear to work equally well (or bad). Both have one classification error. However, a closer look will suggest the prediction of LHS is worse than RHS (why?) For a better assessment, we can treat both the computed result and the target result as distribution and compare them with KL-divergence. Namely

$$KL(p_{target} || p_{computed}) = \sum_{group} p_{target}(group) \log \frac{p_{target}(group)}{p_{computed}(group)}$$
$$= -H(p_{target}) - \sum_{group} p_{target}(group) \log p_{computed}(group)$$

cross entropy

Cross entropy
$$(p \| q) \triangleq \sum_{x} p(x) \log \frac{1}{q(x)} = E_{p}[-\log q(X)]$$
$$= H(p) + KL(p \| q)$$

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- To compute KL-divergence, one needs to find $H(p_{target})$, which is independent of the machine learning system and thus does not reflect the performance of the system
- Thus in practice, cross-entropy is commonly used instead of KL-divergence to measure the performance of a machine learning system

Example: Text processing

• In text processing, it is common that one may need to measure the similarity between two documents D_1 and D_2 .

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Example: Text processing

- In text processing, it is common that one may need to measure the similarity between two documents D_1 and D_2 .
- How to represent documents? One may use the "bag of words". That is, to convert document into a vector of numbers. Each number is the count of a corresponding word
- One can then compares two documents using cross entropy

Cross entropy
$$(p_1 || p_2) = \sum_w p_1(w) \log \frac{1}{p_2(w)},$$

where p_1 and p_2 are the word distributions of documents D_1 and D_2 , respectively

TF-IDF and cross entropy

It may be also interesting of comparing word distribution of a document to the word distribution across all documents That is, let q be the word distribution across all documents,

Cross entropy
$$(p_1 || q) = \sum_{w} p_1(w) \log \frac{1}{q(w)}$$

= $\sum_{w} \underbrace{\frac{\# w \text{ in } D_1}{\text{total } \# \text{ words in } D_1} \log \frac{\text{total } \# \text{ docs}}{\# \text{ doc with } w}}_{TF-IDF(w)}$,

where TF-IDF(w), short for term frequency-inverse document frequency, can reflect how important of the word w to the target document and can be used in search engine

As H(X) is equivalent to the information revealed by X and H(X|Y) the remaining information of X knowing Y, we expect that H(X) - H(X|Y) is the information of X shared by $Y \Rightarrow$ "mutual information"

 $I(X; Y) \triangleq H(X) - H(X|Y)$

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$$I(X; Y) \triangleq H(X) - H(X|Y)$$

Similarly, we can define the "conditional mutual information" shared between X and Y given Z as

$$I(X; Y|Z) \triangleq H(X|Z) - H(X|Y,Z)$$

$I(X;Y) = I(Y;X) \ge 0$

The definition is symmetric and non-negative as desired.

 $I(X; Y) = H(X) - H(X|Y) = E[-\log p(X)] - E[-\log p(X|Y)]$

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= $\sum_{x,y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)} = KL(p(x,y)||p(x)p(y)) \ge 0$

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 $I(X; Y|Z) = H(X|Z) - H(X|Y,Z) = E[-\log p(X|Z)] - E[-\log p(X|Y,Z)]$

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$I(X;Y|Z) = I(Y;X|Z) \ge 0$

The definition is symmetric and non-negative as desired.

$$\begin{split} l(X; Y|Z) &= H(X|Z) - H(X|Y, Z) = E[-\log p(X|Z)] - E[-\log p(X|Y, Z)] \\ &= -\sum_{x,z} p(x,z) \log p(x|z) + \sum_{x,y,z} p(x,y,z) \log p(x|y,z) \\ &= -\sum_{x,y,z} p(x,y,z) \log p(x|z) + \sum_{x,y,z} p(x,y,z) \log p(x|y,z) \\ &= \sum_{x,y,z} p(x,y,z) \log \frac{p(x|y,z)}{p(x|z)} \\ &= \sum_{z} p(z) \sum_{x,y} p(x,y|z) \log \frac{p(x,y|z)}{p(x|z)p(y|z)} \\ &= \sum_{z} p(z) KL(p(x,y|z) \| p(x|z)p(y|z)) \ge 0 \end{split}$$

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Independence and mutual information

$$I(X;Y) = 0 \Leftrightarrow X \bot Y$$

$$I(X; Y) = KL(p(x, y) || p(x)p(y)) = 0$$

implies p(x, y) = p(x)p(y). Therefore $X \perp Y$

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$|I(X; Y|Z) = 0 \Leftrightarrow X \bot Y|Z$

$$I(X; Y|Z) = \sum_{z} p(z) \mathcal{K}L(p(x, y|z) || p(x|z)p(y|z)) = 0$$

implies p(x, y|z) = p(x|z)p(y|z) for all z s.t. p(z) > 0. Therefore $X \perp Y|Z$

Remark

This is just as what we expect. If there is no share information between X and Y, they should be independent!

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Lecture 5 Mutual information

Chain rule for mutual information

$I(X_1, X_2, \cdots, X_N | Y)$

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Chain rule for mutual information

$$I(X_1, X_2, \cdots, X_N | Y) = H(X_1, X_2, \cdots, X_N) - H(X_1, X_2, \cdots, X_N | Y)$$

Chain rule for mutual information

$$I(X_1, X_2, \cdots, X_N | Y)$$

= $H(X_1, X_2, \cdots, X_N) - H(X_1, X_2, \cdots, X_N | Y)$
= $\sum_{i=1}^N H(X_i | X^{i-1}) - H(X_i | X^{i-1}, Y)$

N.B.
$$X^N = X_1, X_2, \cdots, X_N$$

Chain rule for mutual information

$$I(X_1, X_2, \cdots, X_N | Y)$$

= $H(X_1, X_2, \cdots, X_N) - H(X_1, X_2, \cdots, X_N | Y)$
= $\sum_{i=1}^{N} H(X_i | X^{i-1}) - H(X_i | X^{i-1}, Y)$
= $\sum_{i=1}^{N} I(X_i; Y | X^{i-1})$

N.B. $X^N = X_1, X_2, \cdots, X_N$

For continuous X, Y, Z, we can define I(X; Y) = h(X) - h(X|Y) and I(X; Y|Z) = h(X|Z) - h(X|Y, Z)Then, the followings still hold true

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• $I(X; Y|Z) = \int_{z} p(z)KL(p(x, y|z)||p(x|z)p(y|z))dz = I(Y; X|Z) \ge 0$ • $I(X; Y) = 0 \Leftrightarrow X \perp Y$

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•
$$I(X; Y) = KL(p(x, y) || p(x)p(y)) = I(Y; X) \ge 0$$

• $I(X; Y|Z) = \int_{z} p(z) K L(p(x, y|z) || p(x|z) p(y|z)) dz = I(Y; X|Z) \ge 0$

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$$I(X;Y) = 0 \Leftrightarrow X \bot Y$$

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$$I(X_1, X_2, \cdots, X_N | Y) = \sum_{i=1}^N I(X_i; Y | X^{i-1})$$

Conditioning reduces entropy

Given more information, the residual information (uncertainty) should decrease.

Conditioning reduces entropy

Given more information, the residual information (uncertainty) should decrease. More precisely,

 $H(X) \ge H(X|Y)$ $H(X|Y) \ge H(X|Y,Z)$

This is obvious from our previous discussion since $H(X) - H(X|Y) = I(X; Y) \ge 0$ and $H(X|Y) - H(X|Y, Z) = I(X; Z|Y) \ge 0$

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Of course, we also have

 $h(X) \ge h(X|Y)$ $h(X|Y) \ge h(X|Y,Z)$

since $h(X) - h(X|Y) = I(X; Y) \ge 0$ and $h(X|Y) - h(X|Y) = I(X; Z|Y) \ge 0$

Data processing inequality

If random variables X, Y, Z satisfy $X \leftrightarrow Y \leftrightarrow Z$, then

 $I(X;Y) \geq I(X;Z).$

Proof

$$I(X;Y) = I(X;Y,Z) - I(X;Z|Y)$$

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Data processing inequality

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Data processing inequality

If random variables X, Y, Z satisfy $X \leftrightarrow Y \leftrightarrow Z$, then

 $I(X;Y) \geq I(X;Z).$

Proof

$$I(X; Y) = I(X; Y, Z) - I(X; Z|Y)$$

= $I(X; Y, Z)$ (since $X \leftrightarrow Y \leftrightarrow Z$)
= $I(X; Z) + I(X; Y|Z)$
 $\geq I(X; Z)$

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Example (A simple cryptography example)

• Say you have a very personal letter that you don't want to let anyone else except some special someone to read

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 - Letter: plaintext message M
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Remark

Shannon's result: to ensure perfect secrecy, we can show that $H(M) \le H(K)$

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Recall that M, C, K be plaintext message, ciphertext, and key, respectively

Assumption

We will assume here that we have a **non-probabilistic** encryption scheme. In other words, each plaintext message maps to a unique ciphertext given a fixed key. So there is no ambiguity during decoding. Therefore, H(M|C, K) = 0

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Remark (Independence)

For perfect secrecy, one should not be able to deduce anything regarding the message from the ciphertext. Therefore, C and M should be independent.

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Remark (Independence)

For perfect secrecy, one should not be able to deduce anything regarding the message from the ciphertext. Therefore, C and M should be independent. Thus, $I(C; M) = 0 \Rightarrow H(M) = H(M|C) + I(C; M) = H(M|C)$

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Lemma (Entropy bound)

For any **non-probabilistic** encryption scheme, $H(M|C) \leq H(K|C)$

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Recall that for non-probabilistic encryption scheme, $H(M|K, C) = 0 \Rightarrow H(M|C) \le H(M, K|C)$

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Recall that for non-probabilistic encryption scheme, $H(M|K, C) = 0 \Rightarrow$ $H(M|C) \leq H(M, K|C) = H(K|C) + H(M|K, C) = H(K|C)$

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Corollary (Entropy bound)

For any non-probabilistic encryption scheme, $H(M|C) \leq H(K)$

Theorem (Perfect secrecy)

We have perfect secrecy if $H(M) \leq H(K)$

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Lemma (Entropy bound)

For any **non-probabilistic** encryption scheme, $H(M|C) \leq H(K|C)$

Proof.

Recall that for non-probabilistic encryption scheme, $H(M|K, C) = 0 \Rightarrow$ $H(M|C) \leq H(M, K|C) = H(K|C) + H(M|K, C) = H(K|C)$

Corollary (Entropy bound)

For any non-probabilistic encryption scheme, $H(M|C) \leq H(K)$

Theorem (Perfect secrecy)

We have perfect secrecy if $H(M) \leq H(K)$

Proof.

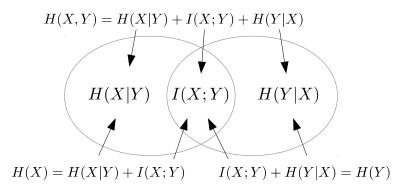
Combine Corollary (Entropy bound) and Remark (Independence)

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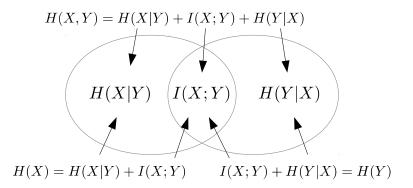
Summary



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Lecture 6

Review



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• Conditioning reduces entropy

- Conditioning reduces entropy
- Chain rules:
 - H(X, Y, Z)

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- Conditioning reduces entropy
- Chain rules:
 - H(X, Y, Z) = H(Z) + H(Y|X) + H(Z|X, Y)
 - H(X, Y, U|V)

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 - I(X, Y, Z; U)

3

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- Data processing inequality: if $X \perp Y | Z$, $I(X; Y) \ge I(X; Z)$
- Independence and mutual information:

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 - $X \perp Y \Leftrightarrow I(X;Y) = 0$
 - $X \perp Y | Z \Leftrightarrow$

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 - $X \perp Y \Leftrightarrow I(X;Y) = 0$
 - $X \perp Y | Z \Leftrightarrow I(X; Y | Z) = 0$
- KL-divergence: $KL(p||q) \triangleq$

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- Chain rules:
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 - $X \perp Y | Z \Leftrightarrow I(X; Y | Z) = 0$
- KL-divergence: $KL(p||q) \triangleq \sum_{x} p(x) \log \frac{p(x)}{q(x)} \ge 0$

This time

- Identification/Decision trees
- Random forests
- Law of Large Number
- Asymptotic equipartition (AEP) and typical sequences



Vampire database

Rumannan Data Dasc	Romanian	Data	Base
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Vampire?	Shadow?	Garlic?	Complexion?	Accent?
No	?	Yes	Pale	None
No	Yes	Yes	Ruddy	None
Yes	?	No	Ruddy	None
Yes	No	No	Average	Heavy
Yes	?	No	Average	Odd
No	Yes	No	Pale	Heavy
No	Yes	No	Average	Heavy
No	?	Yes	Ruddy	Odd

(https://www.youtube.com/watch?v=SXBG3RGr_Rc)

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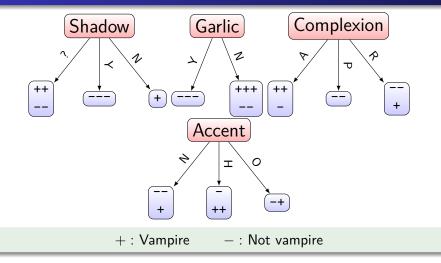
Identifying vampire

Goal: Design a set of tests to identify vampires

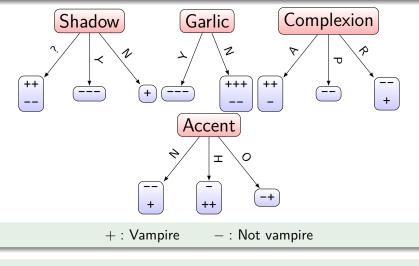
Potential difficulties

- Non-numerical data
- Some information may not matter
- Some may matter only sometimes
- Tests may be costly \Rightarrow conduct as few as possible

Test trees



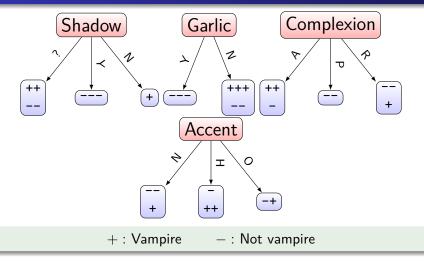
Test trees



How to pick a good test?

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Test trees



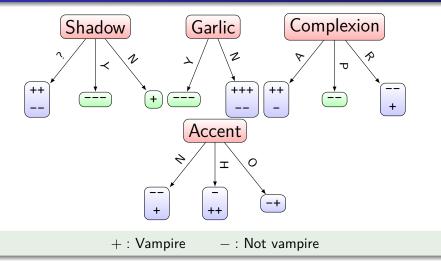
How to pick a good test? Pick test that identifies most vampires (and non-vampires)!

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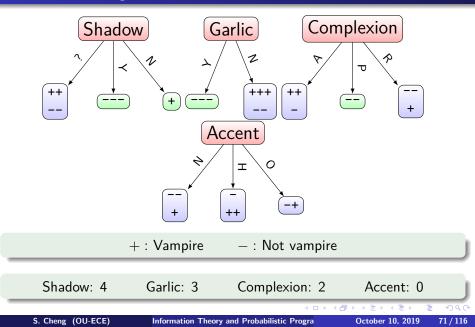
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Sizes of homogeneous sets

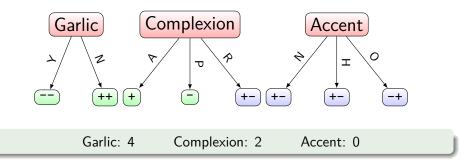


Sizes of homogeneous sets

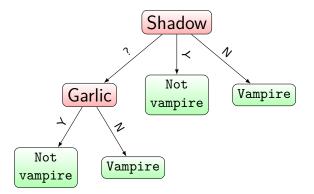


Picking second test

Let say we pick "shadow" as the first test after all. Then, for the remaining unclassified individuals,



Combined tests

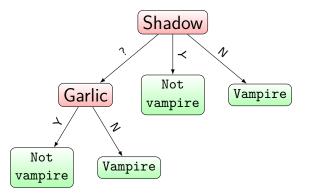


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Combined tests



Problem

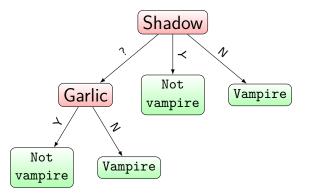
When our database size increases, none of the test likely to completely separate vampire from non-vampire. All tests will score 0 then.

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Combined tests



Problem

When our database size increases, none of the test likely to completely separate vampire from non-vampire. All tests will score 0 then. Entropy comes to the rescue!

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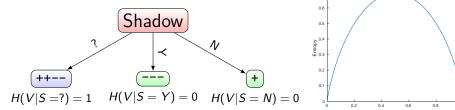
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Consider the database is randomly sampled from a distribution. A set is

- Very homogeneous pprox high certainty
- Not so homogenous pprox high randomness

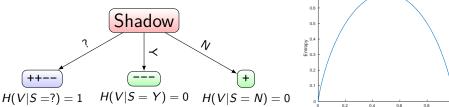
These can be measured with its entropy



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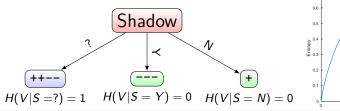
Remaining uncertainty given the test:

$$\frac{4}{8}H(V|S=?)$$

Consider the database is randomly sampled from a distribution. A set is

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These can be measured with its entropy



Remaining uncertainty given the test:

$$\frac{4}{8}H(V|S=?) + \frac{3}{8}H(V|S=Y)$$

0.8

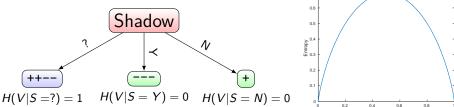
0.2

0.4 0.6

Consider the database is randomly sampled from a distribution. A set is

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Remaining uncertainty given the test:

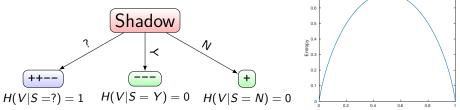
$$\frac{4}{8}H(V|S=?) + \frac{3}{8}H(V|S=Y) + \frac{1}{8}H(V|S=N) = 0.5$$

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Remaining uncertainty given the test:

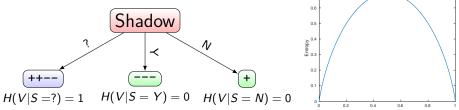
$$\frac{4}{8}H(V|S=?) + \frac{3}{8}H(V|S=Y) + \frac{1}{8}H(V|S=N) = 0.5$$

= $Pr(S=?)H(V|S=?) + Pr(S=Y)H(V|S=Y) + Pr(S=N)H(V|S=N)$

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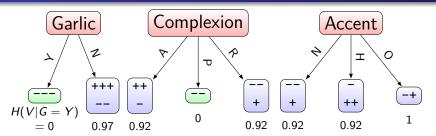
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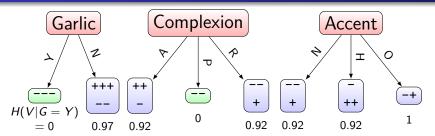
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=Pr(S=?)H(V|S=?) + Pr(S=Y)H(V|S=Y) + Pr(S=N)H(V|S=N)
=H(V|S)



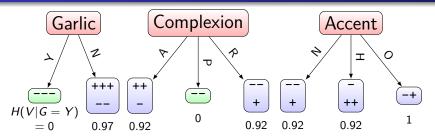
H(V|S) = 0.5



$$H(V|S) = 0.5$$

 $H(V|G) = \frac{3}{8} \cdot 0 + \frac{5}{8} \cdot 0.97 = 0.61$

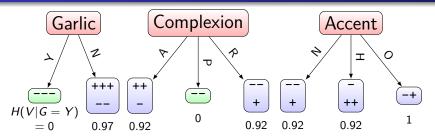
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$$H(V|S) = 0.5$$

$$H(V|G) = \frac{3}{8} \cdot 0 + \frac{5}{8} \cdot 0.97 = 0.61$$

$$H(V|C) = \frac{3}{8} \cdot 0.92 + \frac{2}{8} \cdot 0 + \frac{3}{8} \cdot 0.92 = 0.69$$



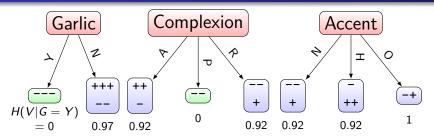
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$$H(V|A) = \frac{3}{8} \cdot 0.92 + \frac{3}{8} \cdot 0.92 + \frac{2}{8} \cdot 1 = 0.94$$

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H(V|S) is maximum. Thus should pick test S first

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Information Theory and Probabilistic Progra

• The test does not need to return discrete result. Let X be the test outcome. It can be continuous as well

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- Build a number of trees instead of a single tree \Rightarrow random forests

Random forests

- Pick random subset of training samples
- Train on each random subset but limited to a subset of features/attributes
- Given a test sample
 - Classify sample using each of the trees
 - Make final decision based on majority vote

Law of Large Number (LLN)

If we randomly sample x_1, x_2, \dots, x_N from an i.i.d. (identical and independently distributed) source, the average of $f(x_i)$ will approach the expected value as $N \to \infty$. That is,

$$\frac{1}{N}\sum_{i=1}^{N}f(x_i)=E[f(X)] \qquad \text{ as } N\to\infty$$

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Example

This is precisely how poll supposes to work! Pollster randomly draws sample from a portion of the population but will expect the prediction matches the outcome

Proof of LLN

The LLN is a rather strong result. We will only show a weak version here

$$Pr\left(\left|\frac{1}{N}\sum_{i=1}^{N}f(X_i)-E[f(X)]\right|\geq a\right)\leq \frac{Var(f(X))}{Na^2}\propto \frac{1}{N}$$

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Markov's Inequality

$$Pr(X \ge b) \le \frac{E[X]}{b}$$
 if $X \ge 0$

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Proof:

$$X = I(X \ge b) \cdot X + I(X < b) \cdot X \ge I(X \ge b) \cdot b$$

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Proof: $X = I(X \ge b) \cdot X + I(X < b) \cdot X \ge I(X \ge b) \cdot b \Rightarrow E[X] \ge Pr(X \ge b) \cdot b$

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Markov's Inequality

$$Pr(X \ge b) \le \frac{E[X]}{b}$$
 if $X \ge 0$

Chebyshev's Inequality

$$Pr(|Y - E[Y]| \ge a) \le \frac{Var(Y)}{a^2}$$

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$$Pr(X \ge b) \le \frac{E[X]}{b}$$
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Chebyshev's Inequality

$$Pr(|Y - E[Y]| \ge a) \le \frac{Var(Y)}{a^2}$$

Proof: Take $X = |Y - E[Y]|^2$ and $b = a^2$, by Markov's Inequality

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Markov's Inequality

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 if $X \ge 0$

Chebyshev's Inequality

$$Pr(|Y - E[Y]| \ge a) \le \frac{Var(Y)}{a^2}$$

Proof: Take
$$X = |Y - E[Y]|^2$$
 and $b = a^2$, by Markov's Inequality
 $Pr(|Y - E[Y]| \ge a) = Pr(|Y - E[Y]|^2 \ge a^2)$
 $\le \frac{E[|Y - E[Y]|^2]}{a^2}$

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Markov's Inequality

$$Pr(X \ge b) \le rac{E[X]}{b}$$
 if $X \ge 0$

Chebyshev's Inequality

$$Pr(|Y - E[Y]| \ge a) \le \frac{Var(Y)}{a^2}$$

Proof: Take
$$X = |Y - E[Y]|^2$$
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By Chebyshev's Inequality,

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$$=\Pr(|Z_{N}-E[Z_{N}]|\geq a)\leq \frac{Var(Z_{N})}{a^{2}}$$

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Consider a sequence of symbols x_1, x_2, \dots, x_N sampled from a DMS and consider the sample average of the log-probabilities of each sampled symbols

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Rearranging the terms, this implies that for any sequence sampled from the source, the probability of the sampled sequence $p(x^N) \rightarrow 2^{-NH(X)}$!

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Set of typical sequences

Let's name the sequence x^N with $p(x^N) \sim 2^{-NH(X)}$ typical and define the set of typical sequences

$$\mathcal{A}_{\epsilon}^{\mathsf{N}}(X) = \{x^{\mathsf{N}} | 2^{-\mathsf{N}(\mathsf{H}(X) + \epsilon)} \le \mathsf{p}(x^{\mathsf{N}}) \le 2^{-\mathsf{N}(\mathsf{H}(X) - \epsilon)}\}$$

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- For any $\epsilon > 0$, we can find a sufficiently large N such that any sampled sequence from the source is typical
- Since all typical sequences have probability $\sim 2^{-NH(X)}$ and they fill up the entire probability space (everything is typical), there should be approximately $\frac{1}{2^{-NH(X)}} = 2^{NH(X)}$ typical sequences

$$(1-\delta)2^{N(H(X)-\epsilon)} \leq |\mathcal{A}_{\epsilon}^{N}(X)| \leq 2^{N(H(X)+\epsilon)}$$

$$1 \ge Pr(X^N \in \mathcal{A}_{\epsilon}^N(X))$$

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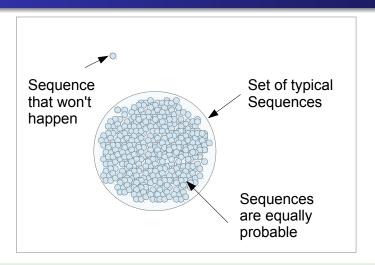
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$$\begin{split} 1 - \delta &\leq \Pr(X^N \in \mathcal{A}_{\epsilon}^N(X)) = \sum_{x^N \in \mathcal{A}_{\epsilon}^N(X)} p(x^N) \leq \sum_{x^N \in \mathcal{A}_{\epsilon}^N(X)} 2^{-N(H(X) - \epsilon)} \\ &= |\mathcal{A}_{\epsilon}^N(X)| 2^{-N(H(X) - \epsilon)} \end{split}$$





Asymptotic equipatition refers to the fact that the probability space is equally partitioned by the typical sequences

S. Cheng (OU-ECE)

Information Theory and Probabilistic Progra

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- AEP (LLN) tells us that it is almost impossible to get, say, a sequence of 100 heads and 900 tails
- AEP also tells us that the number of typical sequences are approximately $2^{NH(X)}$
- Therefore, we can simply assign index to all the typical sequences and ignore the rest. Then we only need $\log 2^{NH(X)} = NH(X)$ to store a sequence of N symbols. And on average, we need H(X) bits per symbol as before!

- Identification/Decision trees
- Random forests
- Law of Large Number
- Asymptotic equipartition (AEP) and typical sequences



This time

- Joint typical sequences
- Covering and Packing Lemmas
- Channel coding setup
- Channel coding rate
- Channel capacity
- Channel Coding Theorem

Jointly typical sequences

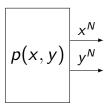
For a pair of sequences x^N and y^N , we say that they are jointly typical if

$$2^{-N(H(X,Y)+\epsilon)} \le p(x^N, y^N) \le 2^{-N(H(X,Y)-\epsilon)}$$

and x^N and y^N themselves are typical

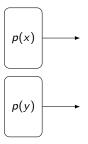
As in the single sequence case,

- Any sequence pair drawing from a joint source p(x, y) is essentially jointly typical
- There are $\sim 2^{NH(X,Y)}$ jointly typical sequences



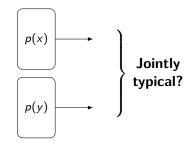
Joint typicality of independent sequences

 Given sequences X^N and Y^N independently drawn from discrete memoryless sources p(x) and p(y)



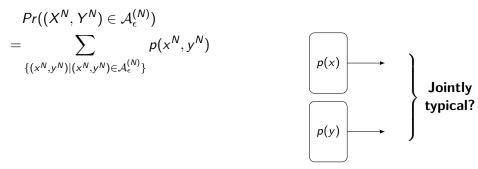
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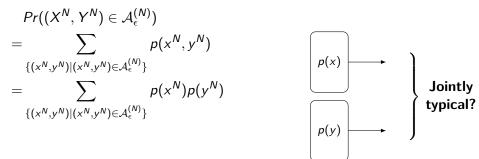
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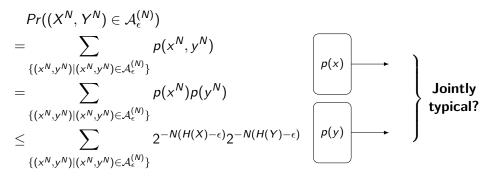
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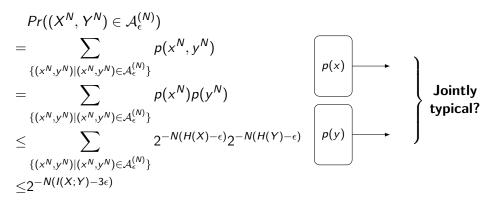
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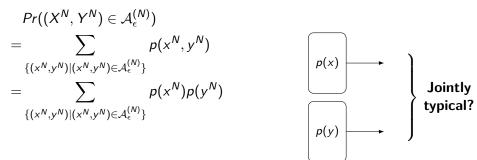
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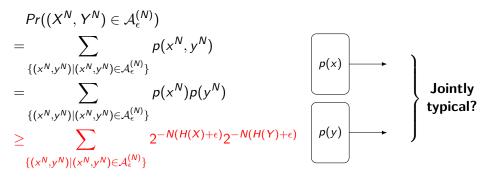
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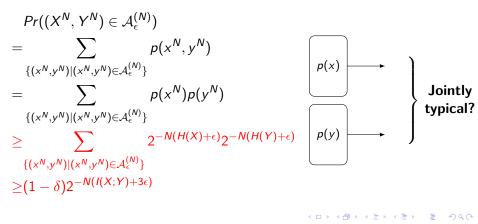
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where $2^{NR} = M$

Since ϵ can be made arbitrarily small as N increases, as long as I(X; Y) > R, we can find a sufficiently large N so that we can "pack" the $M Y^N$ with X^N and none of the Y^N will be jointly typical with X^N

- Again, draw $M(=2^{NR}) Y^N$ sequences
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$$\prod_{m=1}^{M} \left[1 - Pr((X^{N}(m), Y^{N}) \in \mathcal{A}_{\epsilon}^{(N)}(Y, X))\right]$$

$$\leq (1 - (1 - \delta)2^{-N(I(Y;X) + 3\epsilon)})^{M}$$

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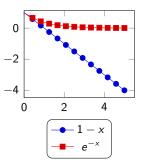
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$$\leq \exp(-M(1 - \delta)2^{-N(I(Y;X)+3\epsilon)})$$

$$\leq \exp(-(1 - \delta)2^{-N(I(Y;X)-R+3\epsilon)}) \rightarrow 0 \text{ as } N \rightarrow \infty \text{ and } R > I(X; Y) + 3\epsilon$$

Summary of packing lemma and covering lemma

Packing Lemma

We can "pack" $M = 2^{NR}$ (with R < I(X; Y)) x^N together without being jointly typical with y^N

Covering Lemma

We can "cover" with $M = 2^{NR}$ (with R > I(X; Y)) x^N such that at least one x^N being jointly typical with y^N

Remark

- Packing lemma is useful in the proof of channel coding theorem
- Covering lemma is useful in the proof of rate-distortion theorem

We will look into the above applications later in this course

p(y|x)

 As the name suggests, the output of a discrete memoryless channel (DMS) only depends on the current input (thus no memoryless). And both its input X and output Y are characterized by the conditional probability p(y|x)

$$\rightarrow p(y|x) \rightarrow$$

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- Given a message m (say generated from a distribution p(m))

$$p(m) \xrightarrow{m} Encoder \xrightarrow{} p(y|x) \xrightarrow{} Decoder$$

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 - The encoder will convert m to x^N suitable for transmission

$$\begin{array}{c} \hline p(m) & \stackrel{m}{\longrightarrow} \hline Encoder & \stackrel{x^N}{\longrightarrow} \hline p(y|x) & \stackrel{y^N}{\longrightarrow} \hline Decoder & \hat{m} \end{array}$$

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- Given a message m (say generated from a distribution p(m))
 - We will have an encoder decoder pair
 - The encoder will convert m to x^N suitable for transmission
 - Decoder will try to extracted the message from the channel output y^N

Channel coding rate

$$\begin{array}{c} p(m) \xrightarrow{m} Encoder \xrightarrow{x^N} p(y|x) \xrightarrow{y^N} Decoder \xrightarrow{} \hat{m} \end{array}$$

The channel coding rate is defined as number of bits of message can be sent per channel use

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- On the other hand, if *R* is larger than the capacity *C*, no matter how we try, it is impossible to recontruct *m* error free
- An intuitive interpretation is that the amount of information can be passed through a channel is just mutual information between the input and output. And since we can pick the statistics of our input, we may make our choice wisely and maximize the mutual information. And the maximum that we can attain is the capacity

$$\begin{array}{c} p(m) & \xrightarrow{m} Encoder? & \xrightarrow{x^N} p(y|x) & \xrightarrow{y^N} Decoder? & \hat{m} \end{array}$$

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$$p(m) \xrightarrow{m} Encoder \xrightarrow{x_{\Delta}^{N}} D/A \xrightarrow{x^{N}} p(y|x) \xrightarrow{y^{N}} A/D \xrightarrow{y_{\Delta}^{N}} Decoder \xrightarrow{h} \hat{m}$$

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$$C_{\Delta} = \max_{p(x)} I(X_{\Delta}; Y_{\Delta}) = \max_{p(x)} H(Y_{\Delta}) - H(Y_{\Delta}|X_{\Delta})$$

$$\approx \max_{p(x)} h(Y) - \log \Delta - h(Y|X_{\Delta}) + \log \Delta$$

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• As $\Delta \to 0$, $C = \max_{p(x)} I(X; Y)$. So expression is completely the same as the discrete case

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• Both input and output are binary (say take value 0 or 1)

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Lecture 7 Channel capacity

Example: Binary symmetric channel

- Both input and output are binary (say take value 0 or 1)
- The channel is symmetric in the sense that

$$p_{Y|X}(1|0) = p_{Y|X}(0|1) = p$$

and

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Channel capacity

Example: Gaussian channel

$$C = \max_{\substack{p(x)\\p(x)}} I(X; Y)$$
$$= \max_{p(x)} h(Y) - h(Y|X)$$

The channel output Y = X + Z, where Z is a zero-mean Gaussian noise (independent of the input X)

$$C = \max_{p(x)} I(X; Y)$$

= $\max_{p(x)} h(Y) - h(Y|X) = \max_{p(x)} h(Y) - h(X + Z|X)$

1

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where SNR is the signal to noise ratio

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$$C = 2W \frac{1}{2} \log(1 + SNR) = W \log\left(1 + \frac{P}{WN_0}\right)$$

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Codebook construction

Forward statement

If the code rate $R < C = \max_{p(x)} I(X; Y)$, according to the Channel Coding Theorem, we should be able to find a code with encoding mapping $\mathbf{c} : m \in \{1, 2, \dots, 2^{NR}\} \rightarrow \{0, 1\}^N$ and the error probability of transmitting any message $m \in \{1, 2, \dots, 2^{NR}\}$, $p_e(m)$, is arbitrarily small

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- The main tool of the proof is random coding
- Let p*(x) = arg max_{p(x)} I(X; Y). Generate codewords from the DMS p*(x) by sampling 2ⁿ length-n sequences from the source:

$$\mathbf{c}(1) = (x_1(1), x_2(1), \cdots, x_N(1))$$
$$\mathbf{c}(2) = (x_1(2), x_2(2), \cdots, x_N(2))$$
$$\cdots$$
$$\mathbf{c}(2^{NR}) = (x_1(2^{NR}), x_2(2^{NR}), \cdots, x_N(2^{NR}))$$

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Decoding

Upon receiving sequence $\mathbf{y} = (y_1, y_2, \cdots, y_N)$, pick the sequence $\mathbf{c}(m)$ from $\{\mathbf{c}(1), \dots, \mathbf{c}(2^{NR})\}$ such that $(\mathbf{c}(m), \mathbf{y})$ are jointly typical. That is $p_{X^N,Y^N}(\mathbf{c}(m),\mathbf{y}) \sim 2^{-n\hat{H}(X,Y)}$. If no such $\mathbf{c}(m)$ exists or more than one such sequence exist, announce error. Otherwise output the decoded message as m

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- Since (C(m), Y) is coming out of the joint source X, Y, P₁ → 0 as n → ∞
- **2** Note that C(M') and **Y** are independent and thus by Packing lemma,

$$P_2 \le 2^{-N(I(X;Y)-R-3\epsilon)} \tag{1}$$

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Since ϵ can be made arbitrarily small as N increase, as long as $I(X; Y) - 3\epsilon > R$, we can make P_2 arbitrarily small also given a sufficiently large N

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A bit more caveat

• We want to show that there exists a code $\mathbf{c}^*(\cdot)$ such that $Pr(error|\mathbf{c}^*, m) \to 0$ no matter what message m is sent

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- Even though the rate reduces from R to $R \frac{1}{N}$ (number of messages from $2^{NR} \rightarrow 2^{NR-1}$). But we can still make the final rate arbitrarily close to the capacity as $N \rightarrow \infty$

- Joint typical sequences
- Covering and Packing Lemmas
- Channel Coding Theorem
- Capacity of Gaussian channel
- Capacity of additive white Gaussian channel
- Forward proof of Channel Coding Theorem

- Converse Proof of Channel Coding Theorem
- Non-white Gaussian Channel
- Rate-distortion problems
- Rate-distortion Theorem

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To continue the converse proof, we will need to introduce a simple result from Fano

Fano's inequality

Denote $Pr(error) = P_e = Pr(M \neq \hat{M})$, then $H(M|Y^N) \leq 1 + P_eH(M)$ Intuitively, if $P_e \rightarrow 0$, on average we will know M for certain given y and thus $\frac{1}{N}H(M|Y^N) \rightarrow 0$

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$$\begin{aligned} H(M|Y^{N}) &= H(M, E|Y^{N}) - H(E|Y^{N}, M) \\ &= H(M, E|Y^{N}) = H(E|Y^{N}) + H(M|Y^{N}, E) \\ &\leq H(E) + H(M|Y^{N}, E) \\ &\leq 1 + P(E=0)H(M|Y^{N}, E=0) + P(E=1)H(M|Y^{N}, E=1) \end{aligned}$$

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Denote $Pr(error) = P_e = Pr(M \neq \hat{M})$, then $H(M|Y^N) \leq 1 + P_eH(M)$ Intuitively, if $P_e \rightarrow 0$, on average we will know M for certain given y and thus $\frac{1}{N}H(M|Y^N) \rightarrow 0$

Proof: Let $E = I(M \neq \hat{M})$, then

$$\begin{aligned} H(M|Y^{N}) &= H(M, E|Y^{N}) - H(E|Y^{N}, M) \\ &= H(M, E|Y^{N}) = H(E|Y^{N}) + H(M|Y^{N}, E) \\ &\leq H(E) + H(M|Y^{N}, E) \\ &\leq 1 + P(E=0)H(M|Y^{N}, E=0) + P(E=1)H(M|Y^{N}, E=1) \\ &\leq 1 + 0 + P_{e}H(M|Y^{N}, E=1) \stackrel{(d)}{\leq} 1 + P_{e}H(M) \end{aligned}$$

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October 10, 2019

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S. Cheng (OU-ECE)

October 10, 2019

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- Without loss of generality, let's consider the discrete approximation, parallel Gaussian channel

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- So our goal is to assign $P_1, P_2, \cdots, P_K \ge 0$ $(\sum_{k=1}^K P_k \le P)$ such that the total capacity

$$\sum_{k=1}^{K} \frac{1}{2} \log \left(1 + \frac{P_k}{\sigma_k^2} \right)$$

is maximize

Let's list all the KKT conditions for the optimization problem

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$$\begin{split} & \frac{\partial}{\partial P_i} \left[\sum_{k=1}^{K} \frac{1}{2} \log \left(1 + \frac{P_k}{\sigma_k^2} \right) + \sum_{k=1}^{K} \lambda_k P_k - \mu \left(\sum_{k=1}^{K} P_k - P \right) \right] = 0 \\ \Rightarrow & \frac{1}{2} \frac{1}{P_i + \sigma_i^2} = \mu - \lambda_i \end{split}$$

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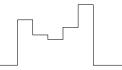
This suggests that $\mu > 0$ and thus $\sum_{k=1}^{K} P_k = P$

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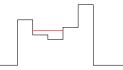
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From $P_i + \sigma_i^2 = const$, power can be allocated intuitively as filling water to a pond (hence "water-filling")

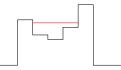
Example



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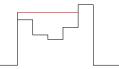


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